

Model Q45D/60D

Auto-Clean Dissolved Oxygen Measurement System

(Q45D SOFTWARE VERSIONS 2.20 AND HIGHER)

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Analytical Technology, Inc. (Manufacturer) warrants to the Customer that if any part(s) of the Manufacturer's products proves to be defective in materials or workmanship within the earlier of 18 months of the date of shipment or 12 months of the date of start-up, such defective parts will be repaired or replaced free of charge. Inspection and repairs to products thought to be defective within the warranty period will be completed at the Manufacturer's facilities in Collegetown, PA. Products on which warranty repairs are required shall be shipped freight prepaid to the Manufacturer. The product(s) will be returned freight prepaid and allowed if it is determined by the manufacturer that the part(s) failed due to defective materials or workmanship.

This warranty does not cover consumable items, batteries, or wear items subject to periodic replacement including lamps and fuses.

Gas sensors, except oxygen sensors, are covered by this warranty, but are subject to inspection for evidence of extended exposure to excessive gas concentrations. Should inspection indicate that sensors have been expended rather than failed prematurely, the warranty shall not apply.

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This warranty is in lieu of all other warranties (including without limiting the generality of the foregoing warranties of merchantability and fitness for a particular purpose), guarantees, obligations or liabilities expressed or implied by the Manufacturer or its representatives and by statute or rule of law.

This warranty is void if the Manufacturer's product(s) has been subject to misuse or abuse, or has not been operated or stored in accordance with instructions, or if the serial number has been removed.

Analytical Technology, Inc. makes no other warranty expressed or implied except as stated above.

Table of Contents

PART 1 - INTRODUCTION	5	PART 7 – SENSOR CLEANING SYSTEM	55
1.1 GENERAL	5	7.1 GENERAL	55
1.2 STANDARD SYSTEM.....	5	7.2 CLEANER SEQUENCE.....	56
1.3 FEATURES	6	PART 8 – PID CONTROLLER DETAILS	58
1.4 Q45D/60D AUTO-CLEAN SYSTEM SPECIFICATIONS.....	9	8.1 PID DESCRIPTION.....	58
1.5 Q45D PERFORMANCE SPECIFICATIONS	10	8.2 PID ALGORITHM	59
PART 2 – MECHANICAL INSTALLATION.....	11	8.3 CLASSICAL PID TUNING	61
2.1 GENERAL	11	8.4 MANUAL PID OVERRIDE CONTROL	61
2.2 WALL MOUNT.....	11	8.5 COMMON PID PITFALLS	62
2.3 RAILING MOUNT.....	13	PART 9 – SYSTEM MAINTENANCE	64
PART 3 – ELECTRICAL INSTALLATION.....	16	9.1 GENERAL	64
3.1 GENERAL	16	9.2 ANALYZER MAINTENANCE	64
3.2 CONNECTIONS	16	9.3 SENSOR MAINTENANCE	64
3.3 RELAY WIRING.....	17	9.3.1 LEAD ANODE REPLACEMENT	65
3.4 REMOTE CLEANER UNIT WIRING	18	SPARE PARTS.....	74
3.5 OPTIONAL HEATER	18		
PART 4 – SENSOR ASSEMBLY	20		
4.1 GENERAL	20		
4.2 SENSOR MODULE	21		
4.4 SENSOR PREPARATION	22		
PART 5 – OPERATION.....	24		
5.1 USER INTERFACE	24		
5.11 KEYS	25		
5.12 DISPLAY.....	25		
5.2 SOFTWARE.....	28		
5.21 SOFTWARE NAVIGATION.....	28		
5.22 MEASURE MENU [MEASURE]	32		
5.23 CALIBRATION MENU [CAL].....	33		
5.25 CONTROL MENU [CONTROL]	37		
5.26 DIAGNOSTICS MENU [DIAG]	44		
PART 6 – CALIBRATION	48		
6.1 GENERAL	48		
6.2 DISSOLVED OXYGEN SPAN CAL (1-SPL)	48		
6.3 DISSOLVED OXYGEN SPAN AIR CAL (%-SAT) ...	50		
6.4 DISSOLVED OXYGEN ZERO CAL	51		
6.5 TEMPERATURE CALIBRATION	53		

Table of Figures

<i>Figure 1 - D.O. System w/Auto-Clean Sensor (ATI-0863)</i>	8
<i>Figure 2 - Wall Mount Monitor Dimensions (ATI-0684)</i>	12
<i>Figure 3 - Handrail Mounting Assembly (ATI-0685)</i>	13
<i>Figure 4 - Submersible Sensor Mounting Assy (ATI-0159)</i>	14
<i>Figure 5 - Mounting Assembly Detail (ATI-189)</i>	15
<i>Figure 6 - Monitor Electrical Connections (ATI-0723)</i>	17
<i>Figure 7 - Remote Electrical Connections (ATI-0798)</i>	19
<i>Figure 8 - Submersible D.O. Sensor Assy (ATI-0679)</i>	20
<i>Figure 9 - Sensing Module Exploded View (ATI-0219)</i>	22
<i>Figure 10 - User Interface (ATI-0654)</i>	24
<i>Figure 11 - Software Map</i>	30
<i>Figure 12 - Control Relay Example</i>	41
<i>Figure 13 - Alarm Relay Example</i>	42
<i>Figure 14 - Cleaner Failure Jumper Map Config (ATI-0582)</i>	57
<i>Figure 15 - Q45D PID Equation</i>	59
<i>Figure 16 - Q45D Display Messages</i>	70
<i>Figure 17 - Pt100 RTD Table</i>	73

Part 1 - Introduction

1.1 General

The Model Q45D/60D is a highly versatile dissolved oxygen instrument designed for the measurement of dissolved oxygen in solution. The full scale operating range of the system is 0-40.0 ppm and the sensing system will operate on water streams with temperatures from 0 to 50°C.

The basic sensing element used in the dissolved oxygen monitor is a galvanic membrane sensor which measures dissolved oxygen directly. The D.O. sensing element is part of a unique self-cleaning sensor assembly that automatically delivers high pressure air to the tip of the sensor to effectively blast accumulated growth from the membrane. Figure 1 shows a typical Auto-Clean D.O. system with necessary interconnections.

1.2 Standard System

The Model Q45D/60D Auto-Clean system includes two main components, a NEMA 4X electronics unit and a submersible D.O. sensor assembly with cleaner nozzle. For special applications, the cleaner system can be supplied separate from the D.O. monitor electronics to allow the D.O. readout to be mounted remote from the sensor and cleaner. Submersible sensors are design for direct immersion in an aeration tank or flowing stream. A 25 ft. cable is potted into the top section of the sensor assembly, and connects directly to the D.O. monitor, or to an intermediate junction box if required. A separate tubing connection located at the top of the sensor assembly is provided for connection of a 25-foot length of plastic tubing (supplied with the unit) between the sensor and the monitor. A typical system is shown in Figure 1.

The D.O. sensor assembly is mounted to a 1" pipe using a special mounting adapter supplied with the system. The 1" pipe is attached to the tank handrail with a bracket assembly that holds the sensor at a slight angle in the tank.

Once installed and placed into operation, the Auto-Clean D.O. sensor will provide months of reliable D.O. measurement in almost any application. Sensors should be checked for build-up after the first 3 months to verify that the cleaner is keeping the membrane clean. However, sensor maintenance intervals of 6 months or more are likely in most aeration tanks.

The sensor cleaning frequency is user programmable, and units are shipped with a default cleaning frequency of once every 24 hours. This frequency has proven sufficient for most aeration applications, but can be increased if needed for a specific application. A cleaning frequency of more than every 2 hours is not recommended. Contact your ATI representative for more information if an 8-hour cleaning cycle does not keep the membrane clean

1.3 Features

- Standard main module is designed to be a fully isolated, line powered instrument. Protected from surge and brownout.
- High accuracy, high sensitivity system, measures from 0.01 ppm to 40.0 ppm through 2 internal automatic ranges.
- Output Hold, Output Simulate, Output Alarm, and Output Delay Functions. All forced changes in output condition include bumpless transfer to provide gradual return to on-line signal levels and to avoid system control shocks on both analog outputs.
- One SPDT relay and two isolated analog outputs. Software settings for relay control include setpoint, deadband, phase, delay, and failsafe.
- Selectable PID controller on main analog output. PID includes manual operation feature, and diagnostic “stuck-controller” timer feature for relay notification of control problems.
- Two analog outputs may be configured to track dissolved oxygen and temperature, or dissolved oxygen and dissolved oxygen. Both analog outputs can be individually programmed to fail to specific values.

- Large, high contrast, custom LCD display with LED back light provides excellent readability in any light conditions. The secondary line of display utilizes 5x7 dot matrix characters for clear message display. Two of four measured parameters may be on the display simultaneously.
- Diagnostic messages provide a clear description of any problem with no confusing error codes to look up. Messages are also included for diagnosing calibration problems.
- Quick and easy one-point sample calibration method, air calibration method, and sensor zero-cal. To provide high accuracy, all calibration methods include stability monitors that check temperature and main parameter stability before accepting data.
- High accuracy Pt1000 temperature input. Temperature element can be user calibrated.
- Security lock feature to prevent unauthorized tampering with transmitter settings. All settings can be viewed while locked, but they cannot be changed.
- High reliability, microprocessor-based system with non-volatile memory. Low mass, surface mount PCB construction containing no adjustment potentiometers. All factory calibrations stored in non-volatile EEPROM.

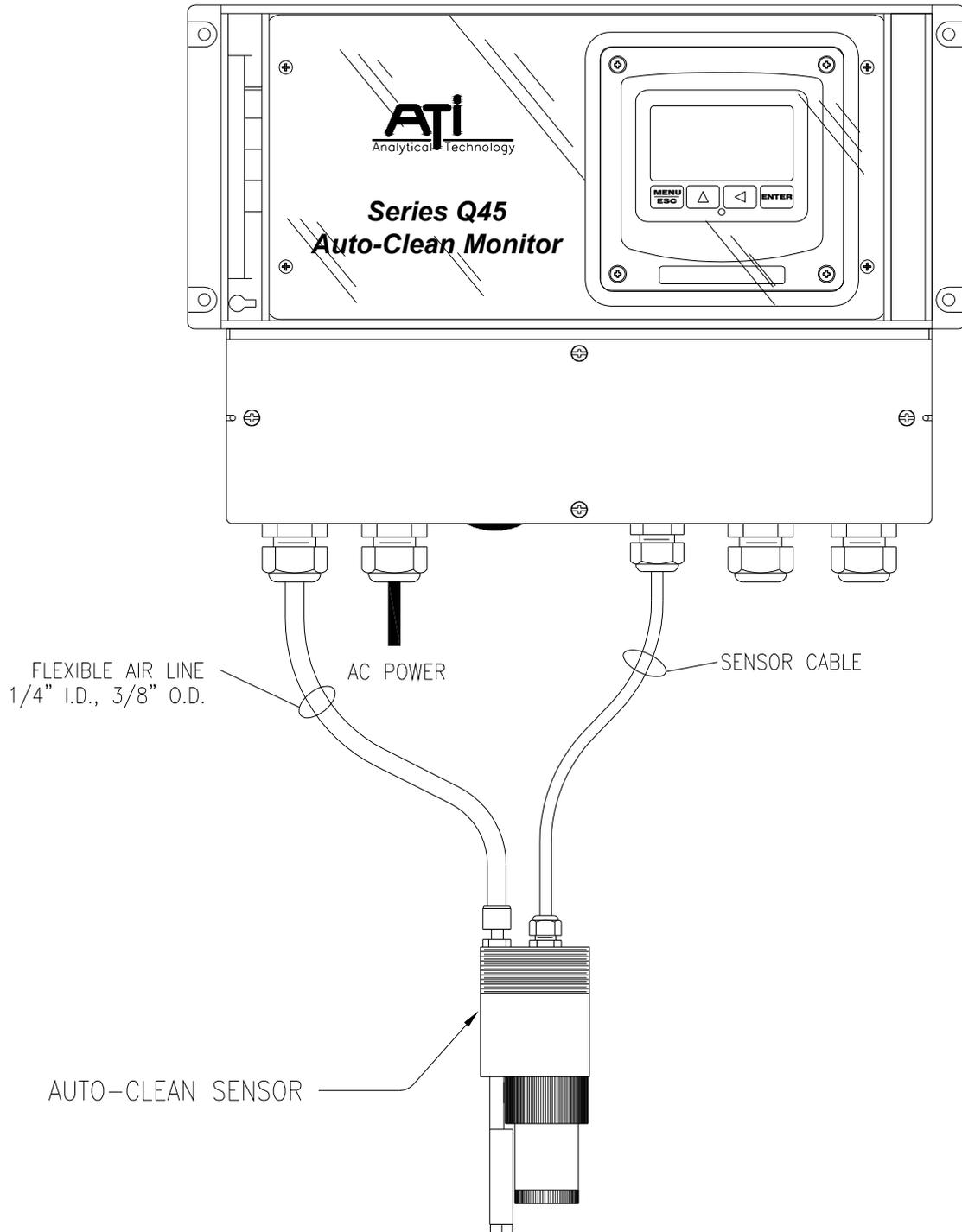


Figure 1 - D.O. System w/Auto-Clean Sensor (ATI-0863)

1.4 Q45D/60D Auto-Clean System Specifications

Displayed Parameters	Main input, 0.00 to 19.99 ppm, 20.0 to 40.0 ppm %Saturation, 0 to 200% Sensor temperature, 0 to 50.0 °C (32 to 122 °F) Sensor Signal -40 to +2000 mVDC Output Values, 4 to 20 mA DC, Out #1/#2 Sensor slope/offset PID controller status Model number and software version
Display	0.75" (19.1 mm) high 4-digit main display with sign 12-digit secondary display, 0.3" (7.6 mm) 5x7 dot matrix. Integral LED back-light for visibility in the dark.
Keypad	4-key membrane type with tactile feedback, polycarbonate with UV coating, integral EMI/static shield and conductively coated window
Enclosure	NEMA 4X, IP65 noryl, stainless steel hardware, weatherproof and corrosion resistant.
Mounting Options	Wall mounted electronic enclosure, Optional handrail mounting brackets.
Conduit Openings	Five cordgrip cable entries provided.
Weight	Electronics Assembly: 15 lbs. (6.8 kg) Sensor Assembly: 3.5 lbs. (1.58 kg.)
Ambient Temperature	Analyzer Service, -20 to 60 °C (-4 to 140 °F) Sensor Service, -5 to 55°C (23 to 131 °F) Storage, -5 to 70 °C (-22 to 158 °F)
Ambient Humidity	0 to 95%, non-condensing
Altitude	Up to 2000 m (6562 ft.)
Location	Designed for hazardous and non-hazardous areas
EMI/RFI Influence	Designed to EN 61326-1
Output Isolation	600 V galvanic isolation
Filter	Adjustable 0-9.9 minutes additional damping to 90% step input
Temperature Input	Pt1000 RTD for automatic compensation

Sensor	2-electrode galvanic membrane sensor for direct measurement of dissolved oxygen, replaceable/rebuildable cartridge
Sensor Materials	Noryl and stainless steel
Sensor Cable	25 ft. (7.5 meter) cable with 6-pin plug. Max sensor-transmitter distance 1000 feet (305 meters) with j-box.
Power	115 or 230 VAC \pm 10%, 50/60 Hz, 300 VA Max.
Fuse	6A slow-blow
Relays	One SPDT, 6-Amp @250VAC, 5-Amp @24 VDC Software selection for setpoint, phase, delay, deadband, hi-lo alarm, and failsafe. Indicators on main LCD.
Analog Outputs	Dual 4-20 mA current loops, 500 Ohms max

1.5 Q45D Performance Specifications

Accuracy	0.2% of span or better
Repeatability	0.05% of span or better
Sensitivity	0.05% of span
Non-linearity	0.1% of span
Stability	0.05% of span per 24 hours, non-cumulative
Temperature Drift	Span or zero, 0.01% of span/ $^{\circ}$ C
Warm-up Time	3 seconds to rated performance
Instrument Response Time	6 seconds to 90% of step input, in a given range, at lowest setting



Equipment bearing this marking may not be discarded by traditional methods in the European community after August 12 2005 per EU Directive 2002/96/EC. End users must return old equipment to the manufacturer for proper disposal.

Part 2 – Mechanical Installation

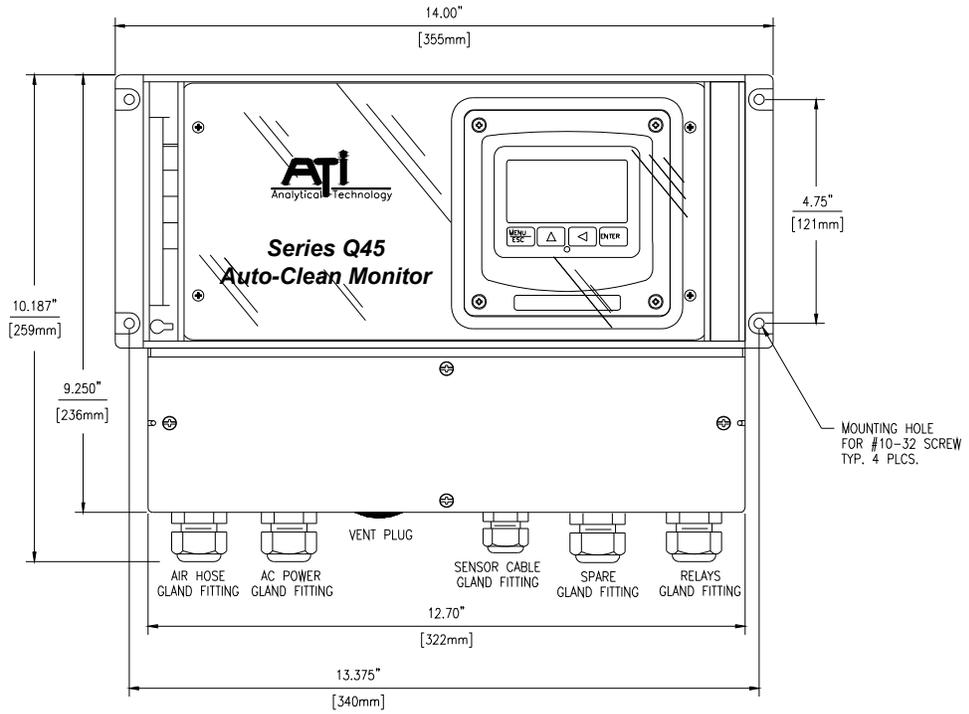
2.1 General

The Q45D Auto-Clean Monitor is housed in a Nema 4X (IP-65) enclosure. The monitor must be mounted near the measurement point, with a maximum of 60 feet between the monitor and the sensor. The standard system is supplied with a 30 ft. sensor cable and 30 feet of air line tubing.

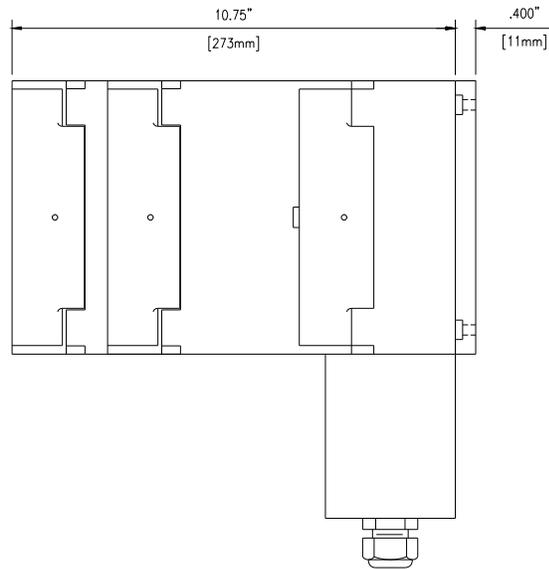
Monitor enclosure may be mounted to any flat surface like a wall or plate. A bracket assembly is available (#00-0930) for mounting the monitor enclosure to aeration handrail systems. This bracket locates the monitor at a convenient height for viewing the display and using the controls.

2.2 Wall Mount

Figure 2 shows the dimensions of the electronic assembly including the hole locations for the enclosure mounting ears. Note that the enclosure mounting brackets are not installed at the factory. They are supplied separately and must be attached using the screws provided. This is done to protect the brackets against shipping damage.



FRONT VIEW



SIDE VIEW

Figure 2 - Wall Mount Monitor Dimensions (ATI-0684)

2.3 Railing Mount

Figure 3 shows the mounting assembly used to mount the electronic monitor to a typical safety handrail that surrounds many aeration tanks. This bracket assembly consists of vertical channels attached to the handrail with u-bolts. The monitor screws to the channels with the 10-32 screws supplied as part of the kit. U-bolts for 2" diameter handrail pipe are also supplied.

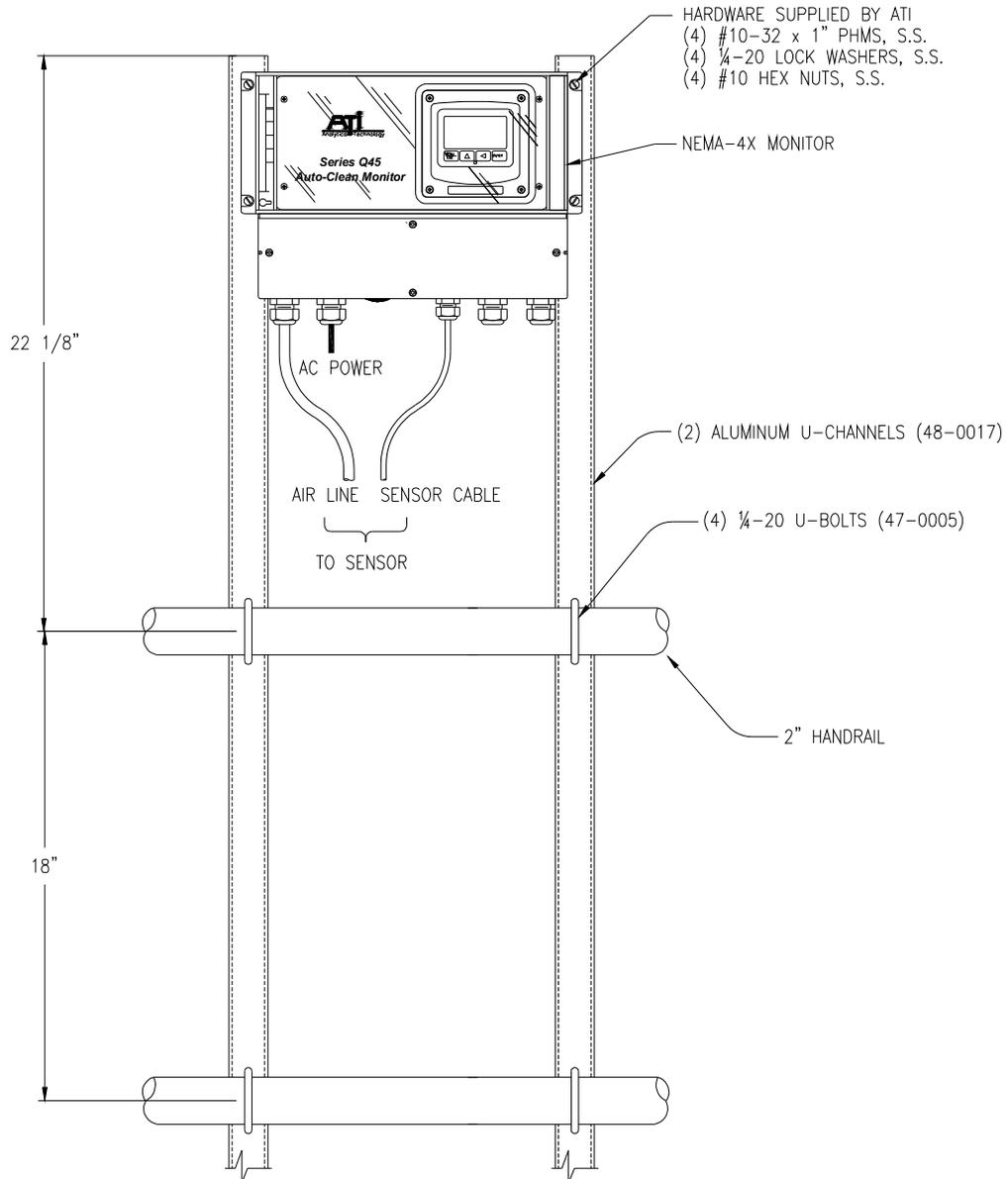


Figure 3 - Handrail Mounting Assembly (ATI-0685)

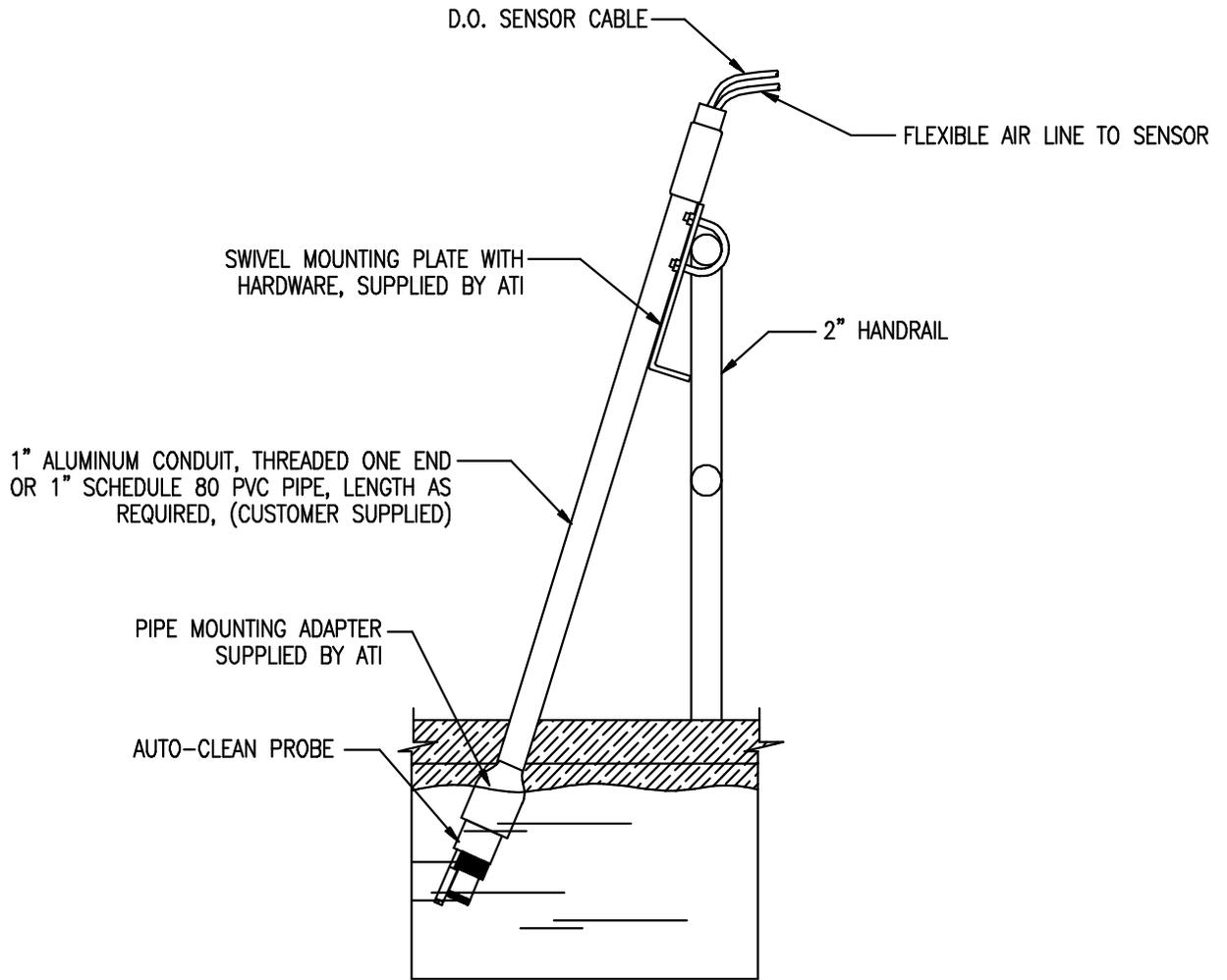


Figure 4 - Submersible Sensor Mounting Assy (ATI-0159)

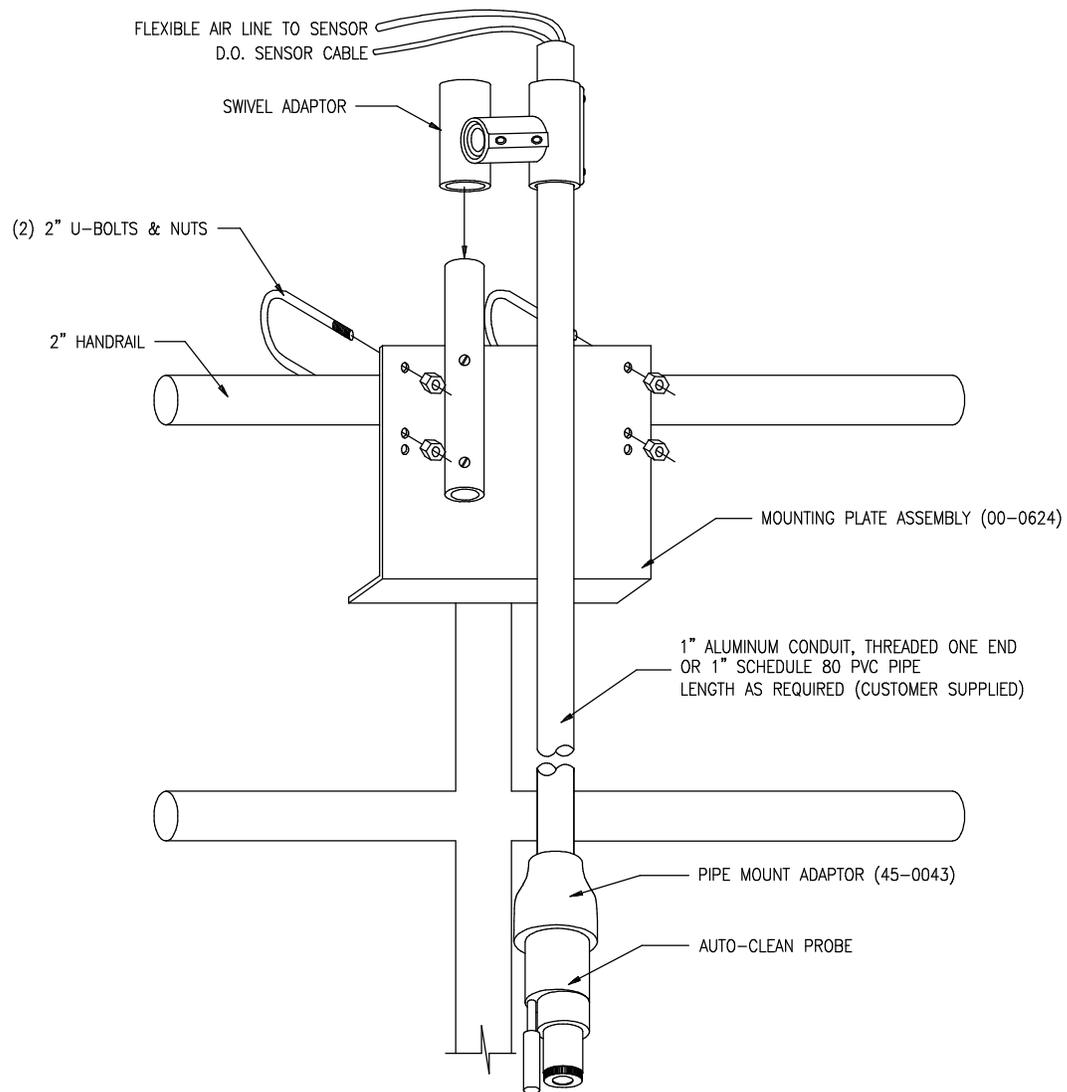


Figure 5 - Mounting Assembly Detail (ATI-189)

Part 3 – Electrical Installation

3.1 General

Q45D/60 Auto-Clean D.O. monitors are powered from either 115 or 230 VAC, 50/60 Hz. Monitors can draw up to 3 amps when the internal air compressor activates as part of the sensor cleaning system. Normal current draw is less than 0.2 amps when the cleaner is off.

Important Notes:

1. Use wiring practices that conform to all national, state and local electrical codes. For proper safety as well as stable measuring performance, it is important that the earth ground connection be made to a solid ground point from **TB1**. The power supply contains a single ¼-Amp slo-blo fuse on the **H** Terminal.
2. Do NOT run sensor cables or instrument 4-20 mA output wiring in the same conduit that contains AC power wiring. AC power wiring should be run in a dedicated conduit to prevent electrical noise from coupling with the instrumentation signals.

3.2 Connections

All wiring connections are made in the terminal compartment at the bottom of the monitor. To access the terminal compartment, loosen the 4 screws holding the cover in place and set the cover aside. The screws are captive and should not come completely out of the plastic cover.

AC power should be brought into the enclosure through the second cordgrip from the left as shown in Figure 6. The left most cordgrip must remain open as this is the entry used for the cleaning system air line.

Sensor and 4-20 mA output connections are made to the terminals in the right side of the terminal compartment as shown.

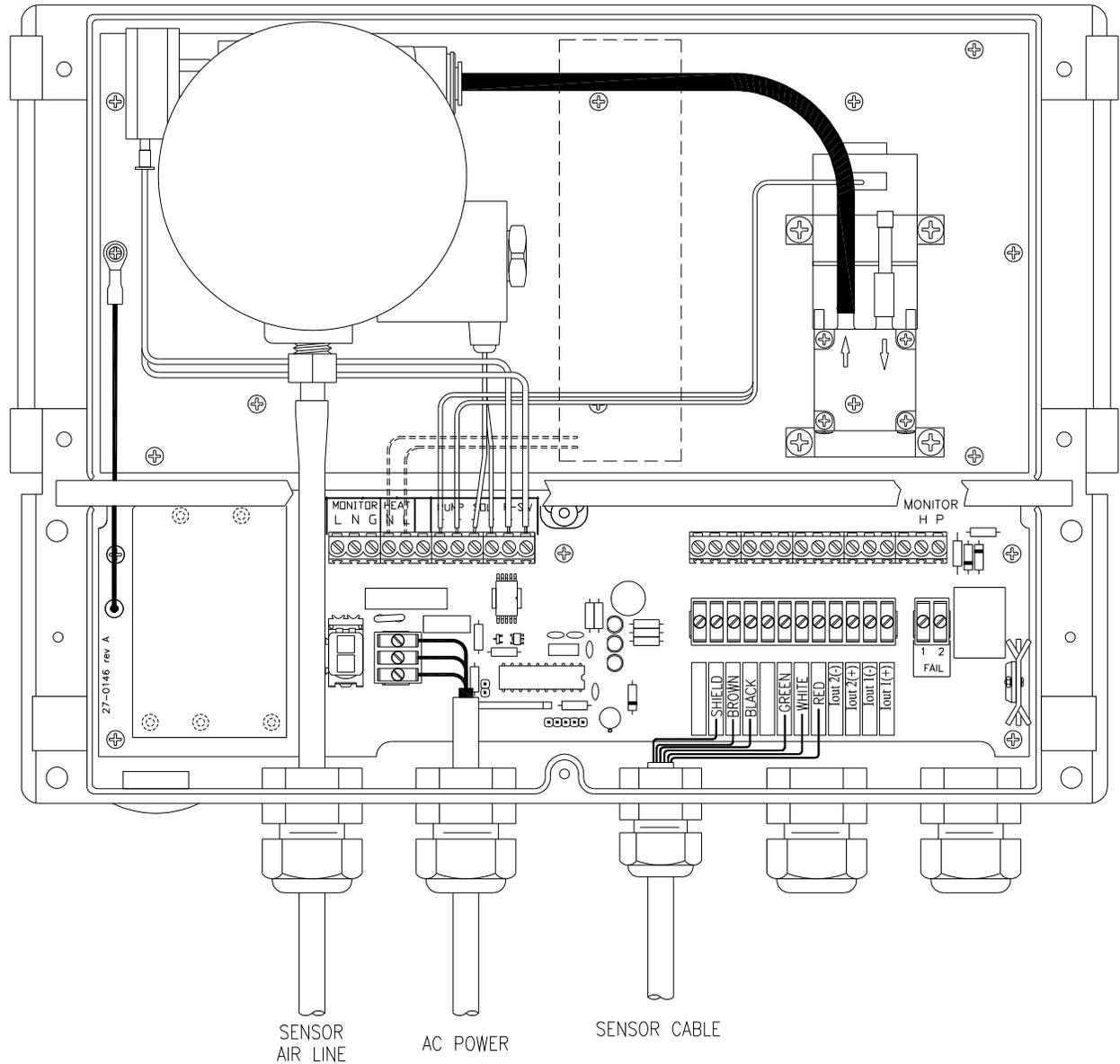


Figure 6 - Monitor Electrical Connections (ATI-0723)

3.3 Relay Wiring

Relay wiring is done to terminal blocks inside the Q45D display assembly. This unit actually contains two SPDT relays, but one of the relays is used to control the activation of the sensor automatic cleaning system. Relay A is available for use as either a control relay, an alarm relay, or as a system failure alarm.

To access the terminals for Relay A, open the front protective cover of the analyzer. Loosen the 4 corner screws for the display unit and the front will hinge down. A terminal block labeled TB3 is accessible. The terminal block will unplug for wiring convenience, and the circuit board is screened to indicate the NO, NC and C contacts.

3.4 Remote Cleaner Unit Wiring

When the remote cleaner unit option is ordered, interconnect the D.O. monitor and the cleaner unit with 7-conductor, 22 AWG shielded cable as shown on Figure 7. Do not run the interconnect cable in the same conduit with AC wiring. The maximum separation between the cleaner unit and the monitor is up to 500 feet.

3.5 Optional Heater

For installations where operating temperatures may regularly fall below 15° F (-10° C), an internal heater strip may be used to insure that the compressor remains warm enough to operate. The diaphragm in the compressor can become quite stiff at very cold temperature resulting in failure of the compressor to start. While this will do no harm, the sensor cleaning function will be compromised.

If factory installed, the heater strip (depicted as a dotted line) will be located as shown in Figure 6 on the previous page, with wires connected as shown. This heater can be added at any time if needed. The thermostatic control for the heater is provided in all units so nothing more need be done except to wire the heater to the terminals as shown. The heater strip has adhesive on one side. Remove the protective paper and stick the strip down to the metal back panel where indicated.

There are no heater adjustments. It will turn on and off automatically when the internal temperature drops below about 32° F (0° C).

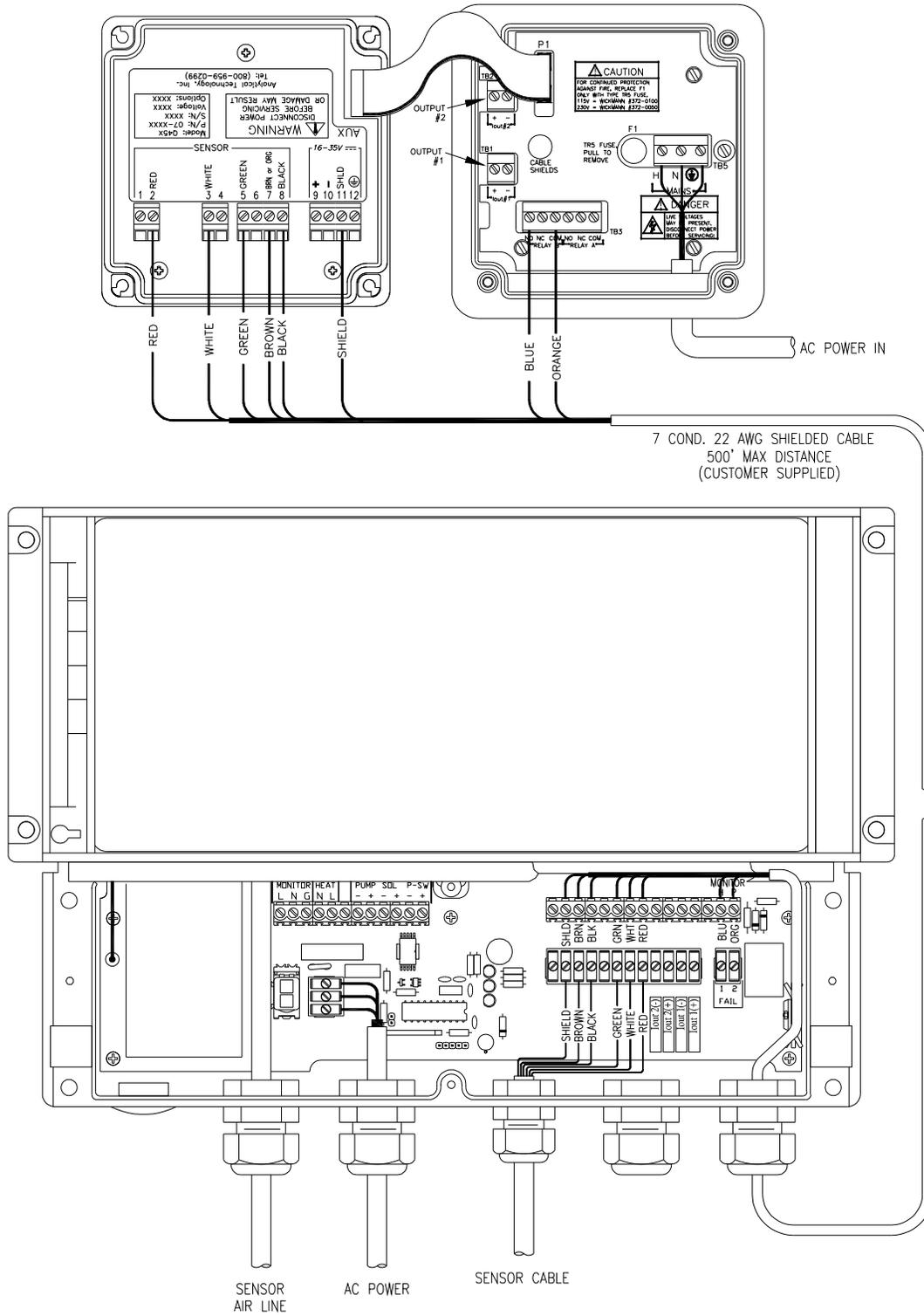


Figure 7 - Remote Electrical Connections (ATI-0798)

Part 4 – Sensor Assembly

4.1 General

Auto-Clean D.O. sensors are actually made up of a number of parts as shown in Figure 8. A holder with 25 feet of cable provides the support for the sensor and cleaner nozzle. The sensing element screws into the bottom of the holder, as does the cleaner nozzle. A soft tube fitting at the top of the holder provides a leak free air connection when used with the 1/4" I.D. x 3/8" O.D. clear PVC tubing supplied with the system.

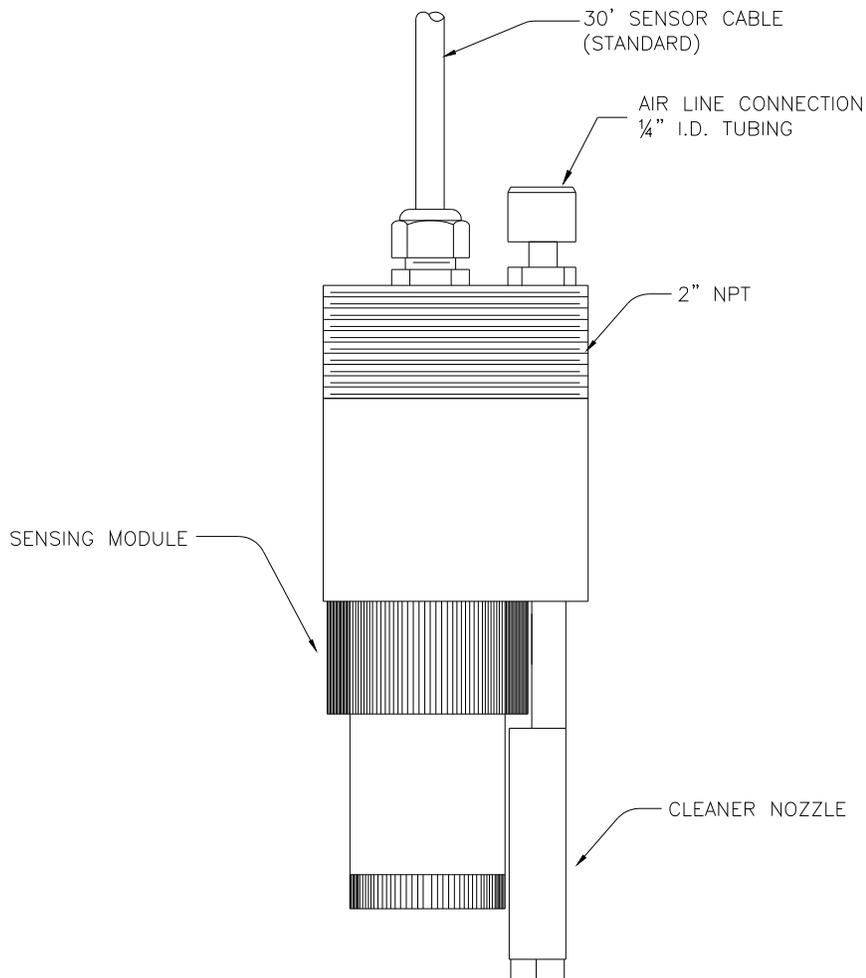


Figure 8 - Submersible D.O. Sensor Assy (ATI-0679)

4.2 Sensor Module

The D.O. sensing module unscrews from the holder. However, **in order to remove the sensing module, the cleaner nozzle must be rotated 180 degrees** so that the module does not hit the machined step on the nozzle. Use a pliers or adjustable wrench to turn the nozzle counterclockwise 180 degrees to allow clearance for the sensing module. Turn the knurled portion of the sensing module counterclockwise to remove.

CAUTION: The o-ring at the top of the sensing module will sometimes stick to the flat surface on the holder. Be sure that the o-ring is in place at the top of the sensing module, or remove it from the holder. This o-ring seal is critical to proper operation, and it must be properly seated in the groove on top of the module prior to screwing it back into the holder.

The dissolved oxygen sensor supplied with the Q45D is shipped dry. It will not operate until it is prepared by adding electrolyte and a membrane. Preparation of the sensor for operation must be done carefully. The procedure should be done by a qualified technician, and it should only be done when the system is ready for operation. Until then, it is best to leave the sensor in the condition in which it is received.

4.4 Sensor Preparation

Preparing a sensor cartridge for use, or rebuilding the cartridge after a period of use, is a quick and simple procedure. The cartridge assembly is shown in Figure 9.

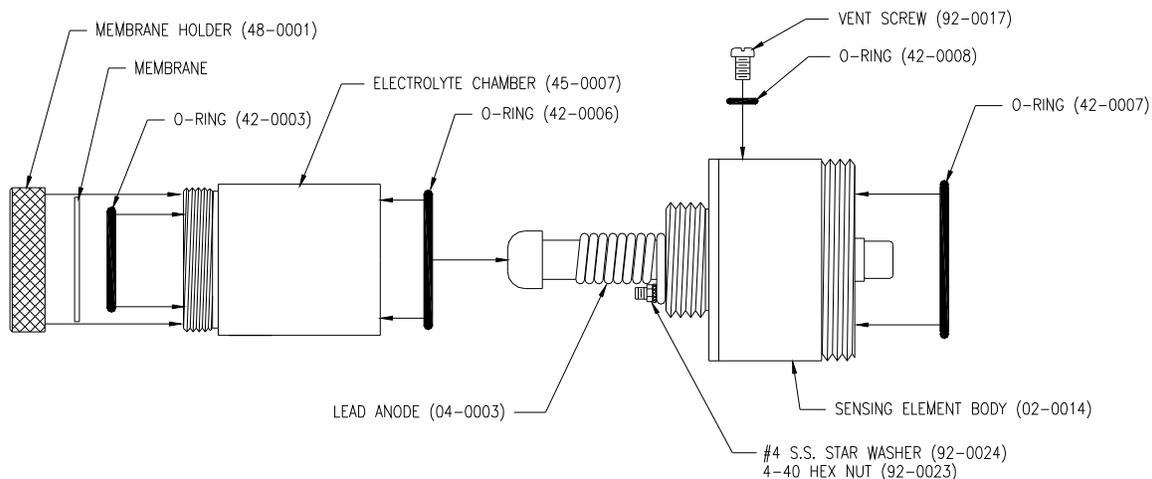


Figure 9 - Sensing Module Exploded View (ATI-0219)

Follow the procedure below to prepare the dissolved oxygen sensor for operation:

- 1) Unscrew the electrolyte chamber from the assembled sensor and also remove the vent screw from the side of the sensor body.
- 2) Remove the front nut from the bottom of the chamber and discard the protective membrane. O-rings are contained in grooves on both the bottom and top of the chamber. Be sure that these o-rings remain in place.
- 3) From the package of membranes supplied with the sensor, place a new membrane into the front nut. **The membrane is clear and is separated from other membranes by a blue paper spacer.**

- 4) Screw the membrane cap onto the canister until you feel the o-ring compress. Hand tight compression is all that is needed. Do not use tools to tighten. The membrane should be flat across the bottom of the canister without wrinkles.
- 5) Fill the canister with electrolyte until the level reaches the bottom of the internal threads in the canister.
- 6) Slowly screw the canister onto the sensor body. A small amount of electrolyte will run out of the hole from which the vent screw was removed. Place a paper towel around the sensor to absorb the electrolyte overflow. The electrolyte is slightly caustic and should be rinsed off of skin if contact occurs. Tighten the canister until the o-ring at the top of the chamber is compressed. Once again, do not use tools to tighten.
- 7) Shake excess electrolyte from the vent hole on the side of the sensor and replace the vent screw.

The sensor cartridge is now ready for operation, and will begin to function as soon as the module is screwed into the holder. The membrane should be stretched tightly across the tip of the sensor. **When handling the assembled sensor, do not set the sensor on its tip or damage to the membrane will result. Severe impacts on the tip of the sensor from dropping or other misuse may cause permanent damage to the sensor.**

Part 5 – Operation

5.1 User Interface

The user interface for the Q45 Series instrument consists of a custom display and a membrane keypad. All functions are accessed from this user interface (no internal jumpers, pots, etc.).

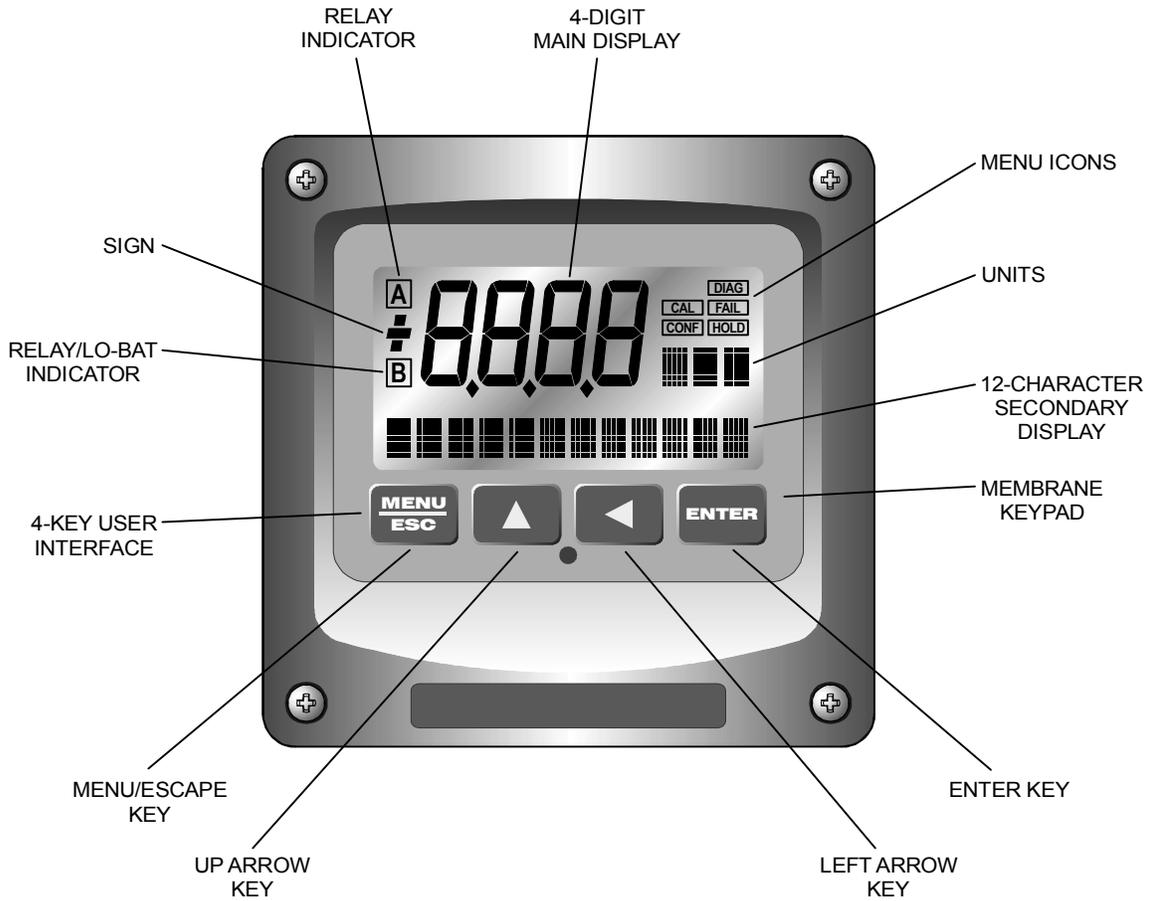


Figure 10 - User Interface (ATI-0654)

5.11 Keys

All user configurations occur through the use of four membrane keys. These keys are used as follows:

- **MENU/ESC** To scroll through the menu section headers or to escape from anywhere in software. The escape sequence allows the user to back out of any changes in a logical manner. Using the escape key aborts all changes to the current screen and backs the user out one level in the software tree. The manual will refer to this key as either MENU or ESC, depending upon its particular function. In the battery-powered version of the Q45, this is also the ON button.
- **UP (arrow)** To scroll through individual list or display items and to change number values.
- **LEFT (arrow)** To move the cursor from right to left during changes to a number value.
- **ENTER** To select a menu section or list item for change and to store any change.

5.12 Display

The large custom display provides clear information for general measurement use and user configuration. There are three main areas of the display: the main parameter display, the secondary message line, and the icon area.

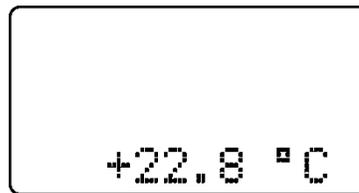
Main Parameter

During normal operation, the main parameter display indicates the present process input with sign and units. This main display may be configured to display any of the main measurements that the system provides. During configuration, this area displays other useful set-up information to the user.



Lower Line

During normal operation, the lower line of the display indicates user-selected secondary measurements that the system is making. This also includes calibration data from the last calibration sequence and the transmitter model number and software version. During configuration, the lower line displays menu items and set-up prompts to the user. Finally, the lower line will display error messages when necessary. For a description of all display messages, refer to Section 9.31.



Icon Area

The icon area contains display icons that assist the user in set-up and indicate important states of system functions. The CAL, CONFIG, CTRL, and DIAG icons are used to tell the user what branch of the software tree the user is in while scrolling through the menu items. This improves software map navigation dramatically. Upon entry into a menu, the title is displayed (such as CAL), and then the title disappears to make way for the actual menu item. However, the icon stays on.



HOLD

The HOLD icon indicates that the current output of the transmitter has been put into output hold. In this case, the output is locked to the last input value measured when the HOLD function was entered. HOLD values are retained even if the unit power is cycled.

FAIL

The FAIL icon indicates that the system diagnostic function has detected a problem that requires immediate attention. This icon is automatically cleared once the problem has been resolved.

Relay Area A/B

The relay area contains two icons that indicate the state of the system relays (if the relay card is installed). If the battery board is installed instead, the B icon indicates that the battery voltage is at a low level. The battery power option and the relay option cannot be installed together.



5.2 Software

The software of the Q45D is organized in an easy to follow menu-based system. All user settings are organized under four menu sections: Measure, Calibration [**CAL**], Configuration [**CONFIG**], Control [**CONTROL**] and Diagnostics [**DIAG**].

Note: The default Measure Menu is display-only and has no menu icon.

5.21 Software Navigation

Within the CAL, CONFIG, CONTROL, and DIAG menu sections is a list of selectable items. Once a menu section (such as CONFIG) has been selected with the MENU key, the user can access the item list in this section by pressing either the ENTER key or the UP arrow key. The list items can then be scrolled through using the UP arrow key. Once the last item is reached, the list wraps around and the first list item is shown again. The items in the menu sections are organized such that more frequently used functions are first, while more permanent function settings are later in the list. See Figure 11 for a visual description of the software.

Each list item allows a change to a stored system variable. List items are designed in one of two forms: simple single variable, or multiple variable sequences. In the single variable format, the user can quickly modify one parameter - for example, changing temperature display units from °F to °C. In the multiple variable sequence, variables are changed as the result of some process. For example, the calibration of dissolved oxygen generally requires more than one piece of information to be entered. The majority of the menu items in the software consist of the single variable format type.

Any data that may be changed will be flashing. This flashing indicates user entry mode and is initiated by pressing the ENTER key. The UP arrow key will increase a flashing digit from 0 to 9. The LEFT arrow key moves the flashing digit from right to left. Once the change has been completed, pressing ENTER again stores the variable and stops the flashing. Pressing ESC aborts the change and also exits user entry mode.

The starting (default) screen is always the Measure Menu. The UP arrow key is used to select the desired display. From anywhere in this section the user can press the MENU key to select one of the four Menu Sections.

The UP arrow icon next to all list items on the display is a reminder to scroll through the list using the UP arrow key.

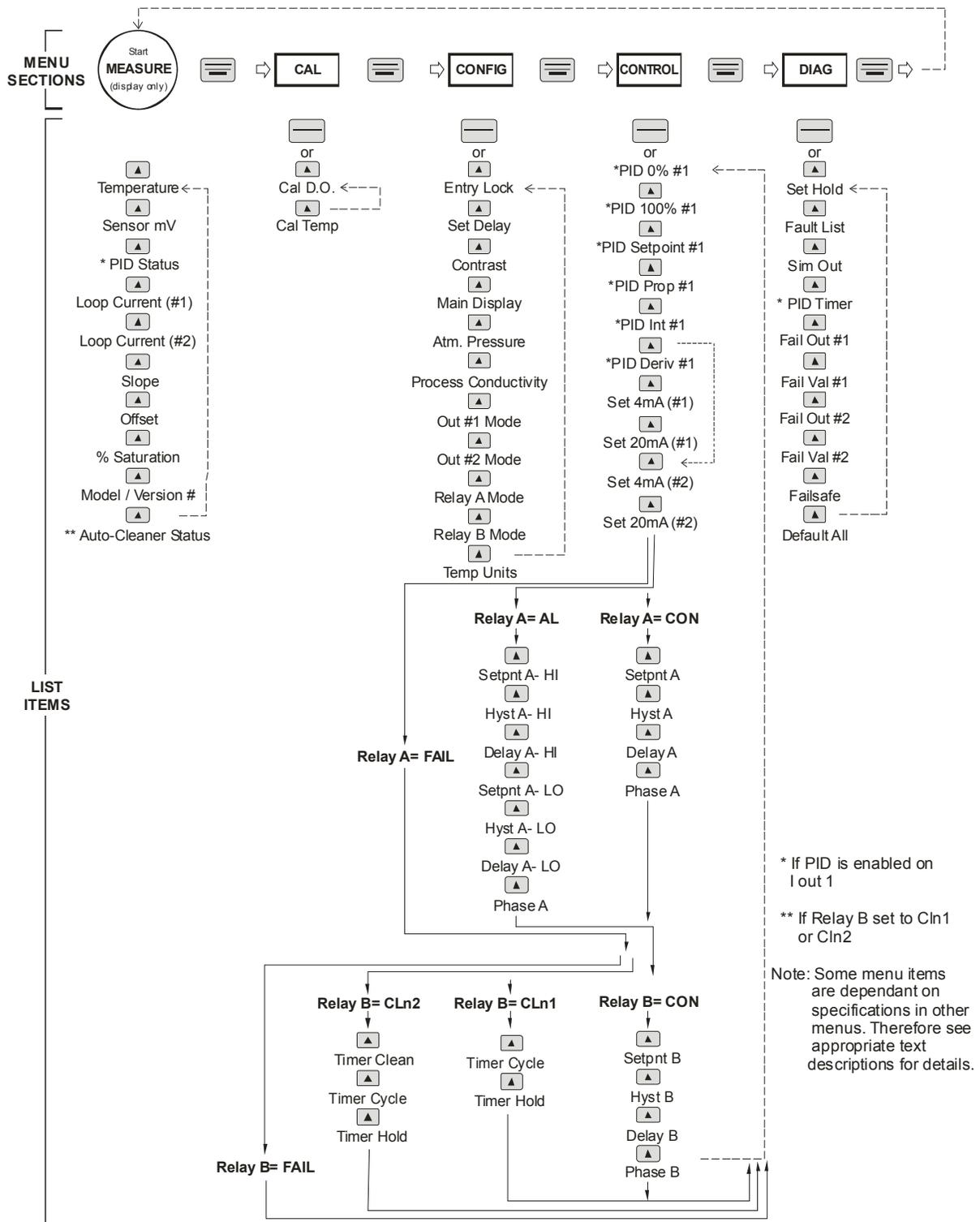


Figure 11 - Software Map

To select a list item for modification, first select the proper menu with the MENU key. Scroll to the list item with the UP arrow key and then press the ENTER key. This tells the system that the user wishes to perform a change on that item. For single item type screens, once the user presses the ENTER key, part or all of the variable will begin to flash, indicating that the user may modify that variable using the arrow keys. However, if the instrument is locked, the transmitter will display the message **Locked!** and will not enter user entry mode. The instrument must be unlocked by entering the proper code value to allow authorized changes to user entered values. Once the variable has been reset, pressing the ENTER key again causes the change to be stored and the flashing to stop. The message **Accepted!** will be displayed if the change is within pre-defined variable limits. If the user decides not to modify the value after it has already been partially changed, pressing the ESC key aborts the modification and returns the entry to its original stored value.

In a menu item which is a multiple variable sequence type, once the ENTER key is pressed there may be several prompts and sequences that are run to complete the modification. The ESC key can always be used to abort the sequence without changing any stored variables.

5.22 Measure Menu [MEASURE]

The default menu for the system is the display-only menu MEASURE. This menu is a display-only measurement menu, and has no changeable list items. When left alone, the instrument will automatically return to this menu after approximately 30 minutes. While in the default menu, the UP arrow allows the user to scroll through the secondary variables on the lower line of the display. A brief description of the fields in the basic transmitter version is as follows:

TRANSMITTER MEAS SCREENS:

- 25.7C** Temperature display. Can be displayed in C or F, depending on user selection. A small "m" on the left side of the screen indicates the transmitter has automatically jumped to a manual 25C setting due to a failure with the temperature signal input.
- +320 mV** Raw sensor millivolt output. Useful for diagnosing problems.
- 100%**
20.00 mA PID Status screen (if enabled.) Shows the present controller output level on left, and actual transmitter current on the right. The controller can be placed in manual while viewing this screen by pressing and holding the ENTER key for 5 seconds until a small flashing "m" appears on the screen. At that point the controller output can be adjusted up or down using the UP and LEFT arrow keys. To return to automatic operation, press and hold the ENTER key for 5 seconds and the "M" will disappear.
- 20.00 mA** Transmitter output current.

Slope = 100%	Sensor output response vs. ideal calibration. This value updates after each calibration. As the sensor ages, the slope reading will decay indicating sensor aging. Useful for resolving sensor problems.
Offset = 0.0 nA	Sensor output current at a zero ppm input. This value updates after a zero-calibration has been performed. Useful for resolving sensor problems.
Q45D0 v1.02	Transmitter software version number.
Tcyc 0.9mn	Auto-Clean status screen (if enabled on relay-based unit.)

For the relay-based analyzer version, the screens are basically the same, with additions to show two analog output instead of one (#1 and #2.)

The MEASURE screens are intended to be used as a very quick means of looking up critical values during operation or troubleshooting.

5.23 Calibration Menu [CAL]

The calibration menu contains items for frequent calibration of user parameters. There are two items in this list: Cal D.O., Cal Temp.

Cal D.O.

The dissolved oxygen calibration function allows the user to adjust the transmitter zero/span reading to match a reference solution, or to set the sensor zero point. See Part 6 - Calibration for more details.

Cal Temp

The temperature calibration function allows the user to adjust the offset of the temperature response by a small factor of ± 5 °C. The temperature input is factory calibrated to very high accuracy. However, long cable lengths and junction boxes may degrade the accuracy of the temperature measurement in some extreme situations. Therefore, this feature is provided as an adjustment. See Part 6 - Calibration for more details.

5.24 Configuration Menu [CONFIG]

The Configuration Menu contains all of the general user settings:

Entry Lock

This function allows the user to lock out unauthorized tampering with instrument settings. All settings may be viewed while the instrument is locked, but they cannot be modified. The Entry Lock feature is a toggle-type setting; that is, entering the correct code will lock the transmitter and entering the correct code again will unlock it. The code is preset at a fixed value of 1454. Press ENTER to initiate user entry mode and the first digit will flash. Use arrow keys to modify value. Press ENTER to toggle lock setting once code is correct. Incorrect codes do not change state of lock condition.

Set Delay

The delay function sets the amount of damping on the instrument. This function allows the user to apply a first order time delay function to the dissolved oxygen measurements being made. Both the display and the output value are affected by the degree of damping. Functions such as calibration are not affected by this parameter. The calibration routines contain their own filtering and stability monitoring functions to minimize the calibration timing. Press ENTER to initiate user entry mode, and the value will flash. Use the arrow keys to modify value; range is 0.1 to 9.9 minutes. Press ENTER to store the new value.

Contrast

This function sets the contrast level for the display. The custom display is designed with a wide temperature range, Super-Twist Nematic (STN) fluid.

The STN display provides the highest possible contrast and widest viewing angle under all conditions. Contrast control of this type of display is generally not necessary, so contrast control is provided as a means for possible adjustment due to aging at extreme ranges. In addition, the display has an automatic temperature compensation network. Press ENTER to initiate user entry mode, and the value will flash. Use arrow keys to modify the value; range is 0 to 8 (0 being lightest). Press ENTER to update and store the new value.

Top Display

This function allows the user to change the measurement in the primary display area. The user may select between dissolved oxygen in ppm, %saturation, sensor temperature, or output signal #1. Using this function, the user may choose to put temperature in the main display area and dissolved oxygen on the secondary, lower line of the display. Press ENTER to initiate user entry mode, and the entire value will flash. Use the UP arrow key to modify the desired display value. Press ENTER to store the new value.

Atm Pres

The Q45D instrument utilizes the atmospheric pressure value as an input for the calculation of a theoretical ppm value during a saturation calibration. The input default units are inHg (inches Mercury) since these units are easy to obtain from most local weather services. This value is only required to be entered during initial installation – it does not need to be modified at every calibration. Press ENTER to initiate user entry mode and the entire value will flash. Use the arrow keys to modify the value; range is 20.00 to 31.50 inHg.

A reference table is provided in Section 9 to convert to inHg from several other common air pressure units. Press ENTER to store the new value.

Proc Cond

The Q45D instrument also utilizes the process conductivity value as an input for the calculation of a theoretical ppm value during a saturation calibration. This value is only required to be entered during initial installation - it does not need to be modified at every calibration. Press ENTER to initiate user entry mode and the value will flash. Use the arrow keys to modify the value; range is 0.00 to 76.00 mS/cm. Press ENTER to store the new value.

Note: If the user will not be changing solution conductivity dramatically during the calibration process, leave a default setting of 00.50 mS/cm.

Out#1 Mode

This function sets analog output #1 to either track D.O. (default) or enables the PID controller to operate on the D.O. input.

Press ENTER to initiate user entry mode, and the entire value will flash. Use the UP arrow key to modify the desired value; selections include 1-ppm for D.O. tracking or 2-PID for D.O. PID control. Press ENTER to store the new value.

Out#2 Mode

This function sets analog output #2 to either track temperature (default), or dissolved oxygen. Press ENTER to initiate user entry mode, and the entire value will flash. Use the UP arrow key to modify the desired value; selections include 1-C/F for temperature tracking, or 2-ppm for dissolved oxygen tracking. Press ENTER to store the new value.

*Rly A Mode

Relay A can be used in three different ways: as a setpoint control, as a fail alarm, or as a HI-LO alarm band. The three settings for Rly A Mode are **CON**, **FAIL** and **AL**.

The **CON** setting enables normal control operation for Relay A, with settings for setpoint, hysteresis, delay and phasing appearing in the CONFIG menu automatically. See Figure 12 for further details.

The **FAIL** setting enables the fail alarm mode for Relay A. Relay A will then trip on any condition that causes the FAIL icon to be displayed on the LCD. Using this mode allows the User to send alarm indications to other remote devices.

The **AL** setting allows two setpoints to be selected for the same relay, producing a HI-LO alarm band. In this mode, Relay A will trip inside or outside of the band, depending upon the Phase selected. See Figure 13 for further details.

Relay B Mode

Relay B in Auto-Clean Monitors is used to activate the air-wash cleaning system that keeps the sensor operating properly. This relay should normally be set to **CLn1** Mode for normal cleaning. Do not change the factory setting for this relay without first consulting ATI or your ATI representative.

Temp Units

This function sets the display units for temperature measurement. Press ENTER to initiate user entry mode, and the entire value will flash. Use the UP arrow key to modify the desired display value. The choices are °F and °C. Press ENTER to store the new value.

5.25 Control Menu [CONTROL]

The Control Menu contains all of the output control user settings:

Set 4 mA
Set 20 mA
[Out1=D.O.]

These functions set the main 4 and 20 mA current loop output points for the transmitter. The units displayed depend on the selection made in the CONFIG menu for Out #1 Mode. Also, when the Relay Option Board is installed, the units will also display **#1 or #2** – since there are actually two analog outputs present in this version.

The value stored for the 4 mA point may be higher or lower than the value stored for the 20 mA point.

The entry values are limited to values within 0 to 40.00 ppm, and the 4 mA and the 20 mA point must be separated by at least 1% of this range. Use the LEFT arrow key to select the first digit to be modified. Then use the UP and LEFT arrow keys to select the desired numerical value. Press ENTER to store the new value.

Set PID 0%
Set PID 100%
[Out1=PID]

If the PID is enabled, this function sets the minimum and maximum controller end points. Unlike the standard 4-20 mA output, the controller does not “scale” output values across the endpoints. Rather, the endpoints determine where the controller would normally force minimum or maximum output in an attempt to recover the setpoint (even though the controller can achieve 0% or 100% anywhere within the range.)

If the 0% point is lower than the 100% point, then the controller action will be “reverse” acting. That is, the output of the controller will increase if the measured value is less than the setpoint, and the output will decrease if the measured value is larger than the setpoint. Flipping the stored values in these points will reverse the action of the controller to “direct” mode.

The entry value is limited to a value within the range of 0 to 40.00 ppm, and the 0% and the 100% point must be separated by at least 1% of this range. Use the LEFT arrow key to select the first digit to be modified. Then use the UP and LEFT arrow keys to select the desired numerical value. Press ENTER to store the new value.

PID Setpnt
[Out1=PID]

The measured value which the controller is attempting to maintain by adjusting output value. It is the nature of the PID controller that it never actually gets to the exact value and stops. The controller is continually making smaller and smaller adjustments as the measured value gets near the setpoint.

PID Prop
[Out1=PID]

Proportional gain factor. The proportional gain value is a multiplier on the controller error (difference between measured value and setpoint value.) Increasing this value will make the controller more responsive.

PID Int

[Out1=PID]

Integral is the number of “repeats-per-minute” of the action of the controller.

It is the number of times per minute that the controller acts on the input error. At a setting of 2.0 rpm, there are two repeats every minute. If the integral is set to zero, a fixed offset value is added to the controller (manual reset.) Increasing this value will make the controller more responsive.

PID Deriv

[Out1=PID]

Derivative is a second order implementation of Integral, used to suppress “second-order” effects from process variables. These variables may include items like pumps or mixers that may have minor impacts on the measured value. The derivative factor is rarely used in water treatment process, and therefore, it is best in most cases to leave it at the default value. Increasing this value will make the controller more responsive.

Set 4 mA #2**Set 20 mA #2**

[temp/D.O.]

These functions set the second 4 mA and 20 mA current loop output points for the transmitter. The output may be set to track temperature (default), or dissolved oxygen. The values stored for the 4 mA point may be higher or lower than the value stored for the 20 mA point.

The entry value must be between 0 and 55 °C if it is set for temperature, within the range of 0 to 40.00 ppm if the output is set to track dissolved oxygen. The 4 mA and the 20 mA point must be at least 20 units away from each other. Press ENTER to initiate user entry mode, and the value will flash. Use arrow keys to modify value. Press ENTER to store the new value.

NOTE: If the temperature units are changed between °C and °F (see Temp Units in this section), the default settings for this output will be stored (present data is not converted.)

A Setpoint

This function establishes the dissolved oxygen trip point for relay A.

The entry value is limited to a value within the range of 0 to 40.00 ppm. Use the LEFT arrow key to select the first digit to be modified. Then use the UP and LEFT arrow keys to select the desired numerical value. Press ENTER to store the new value.

A Hysteresis

This function establishes the hysteresis, or “deadband”, for Relay A. Hysteresis is most often used to control relay chattering; however, it may also be used in control schemes to separate the ON/OFF trip points of the relay.

Press ENTER to initiate user entry mode, and the value will flash. Use the arrow keys to modify value. Press ENTER to store the new value.

A Delay

This function places an additional amount of time delay on the trip point for relay A. This delay is in addition to the main delay setting for the controller. The entry value is limited to a value between 0 and 999 seconds. Press ENTER to initiate user entry mode, and the value will flash. Use arrow keys to modify value; range is 0 to 999 seconds. Press ENTER to store the new value.

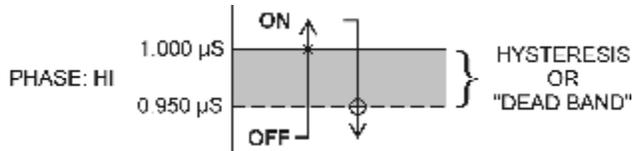
A Phasing

This function establishes the direction of the relay trip. When phase is HI, the relay operates in a direct mode. Therefore, the relay energizes and the LCD indicator illuminates when the dissolved oxygen value **exceeds** the setpoint. When the phase is LO, the relay energizes and the LCD indicator illuminates when the dissolved oxygen level drops **below** the setpoint. The failsafe setting does have an impact on this logic. The description here assumes the failsafe setting is OFF.

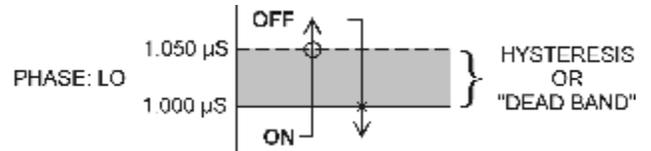
Press ENTER to initiate user entry mode, and the entire value will flash. Use the UP arrow key to modify the desired value; selections include **HI** for direct operation or **LO** for reverse operation. Press ENTER to store the new value.

See Figure 12 below for a visual description of a typical control relay application.

When value rises to ≥ 1.000 ppm, relay



When value rises to ≥ 1.050 ppm.



When value falls to ≤ 0.950 ppm, relay

When value falls to ≤ 1.000 ppm, relay

Settings:

Setpoint:	1.000 ppm
Hyst:	0.050
Delay:	000
Failsafe:	OFF

Figure 12 - Control Relay Example

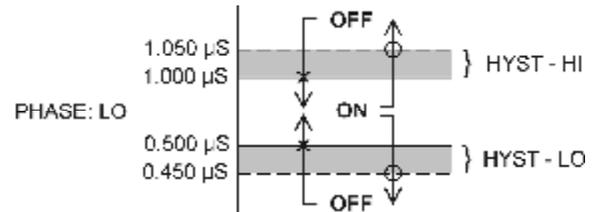
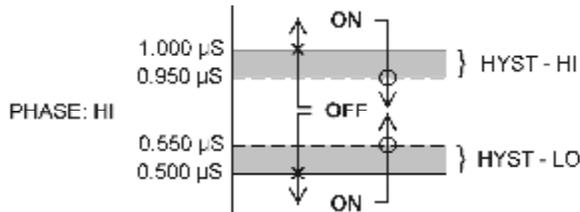
- Setpnt A-HI**
- Hyst A-HI**
- Delay A-HI**
- Setpnt A-LO**
- Hyst A-LO**
- Delay A-LO**

If Relay A Mode is set to Alarm Mode, **AL**, then the following settings will appear in the Config Menu list automatically. In this mode, two setpoints can be selected on the same relay, to create an alarm band. Phase HI selection causes the relay to energize outside of the band, and Phase LO causes the relay to energize inside of the band. This feature enables one relay to be used as a control relay while the other is used as a HI-LO Alarm relay at the same time. Setpoint A-LO must be set lower than Setpoint A-HI. When AL mode is first selected, Setpoint A-LO is defaulted to 0.

Figure 13 is a visual description of a typical alarm relay application.

When value rises to ≥ 1.000 ppm, relay closes, until value falls back to ≤ 0.950 ppm.

When value falls to ≤ 1.000 ppm, relay closes, until rises back to ≥ 1.050 ppm.



When value falls to ≤ 0.500 ppm, relay closes, until rises back to ≥ 0.550 ppm.

When value rises to ≥ 0.500 ppm, relay closes, until value falls back to ≤ 0.450 ppm.

Settings:

SetpointA-HI:	1.000 ppm
Hyst A-HI:	0.050
Delay A-HI:	000
SetpointA-LO:	.500 ppm
Hyst A-LO:	.050
Delay A-LO:	000

Figure 13 - Alarm Relay Example

- *Timer B CLEAN
- *Timer B CYCLE
- *Timer B HOLD

When Relay B is set to **CLn1** mode (Factory Default), Submenu **Timer B CLEAN** is not active. When Relay B is set to **CLn2** (For Customer supplied Air Delivery Source) all three submenu Timer B settings appear in the CONTROL menu list.

Relay B will toggle open/closed based on the time settings entered by the user. The timer **CLEAN** setting controls the amount of time that Relay B is engaged (N.O. contact closed), and the timer **CYCLE** setting controls the amount of time that Relay B is released (N.O. contact open.)

The timer **HOLD** setting allows an output hold time to be entered into the cleaning cycle. This hold time allows the outputs to stabilize back to normal readings before the outputs are released from their “hold” state. Using this feature properly avoids disturbing any instruments connected to the outputs during the cleaning cycle – where D.O. readings can fluctuate.

To change the values for Timer **CLEAN**, **CYCLE**, and **HOLD**, press ENTER to initiate user entry mode, and entire value will flash. Use the UP arrow key to modify the desired value. Selections for each variable are: CLEAN 1-10 minutes, CYCLE 1-999 hours, HOLD 0-999 minutes. Press ENTER to store the new value.

Example: If the timer-CLEAN setting is 1 minute, the timer CYCLE setting is 24 hours, and the timer-HOLD setting is 3 minutes, the following sequence will occur: At the instant the timer is enabled (or data for the CLEAN/CYCLE/HOLD is modified) the “CYCLE” time period begins. Once the 24-hour CYCLE period ends, the outputs will be put in hold and relay B will engage for 1 minute (CLEAN time.) After the 1 minute has expired, relay B will be released but the hold will stay locked in for an additional 3 minutes (HOLD time), retaining the original output signals. Once the 3 minutes expire, the outputs will be released back to the normal monitoring state. Then, the entire cycle will repeat – approximately once per day.

Note: The sensor wash timer is not based on a “real-time” clock circuit. Therefore, the time accuracy is only within about 10 minutes per day.

Note: A timer wash cycle can be manually started by pressing and holding the ENTER key for a few seconds while viewing the timer status screen in the MEAS menu. The timer must be in the “Tcyc” state to allow a manual start. After this forced cycle, the system will return to normal.

If the B mode selection is changed while the sensor wash timer is in mid-cycle (and the HOLD is enabled), the HOLD must be turned off manually to return all of the outputs to normal operation. A flashing “T” will be seen on the lower line of the display next to temperature while the probe cleaner function is operating.

5.26 Diagnostics Menu [DIAG]

The diagnostics menu contains all of the user settings that are specific to the system diagnostic functions, as well as functions that aid in troubleshooting application problems.

Set Hold

The Set Hold function locks the current loop output values on the present process value. This function can be used prior to calibration, or when removing the sensor from the process, to hold the output in a known state. Once HOLD is released, the outputs return to their normal state of following the process input.

The transfer out of HOLD is bumpless on the both analog outputs - that is, the transfer occurs in a smooth manner rather than as an abrupt change. An icon on the display indicates the HOLD state, and the HOLD state is retained even if power is cycled. Press ENTER to initiate user entry mode, and entire value will flash. Use the UP arrow key to modify the desired value, selections are **ON** for engaging the HOLD function, and **OFF** to disengage the function. Press ENTER to store the new value.

Note: When the Relay Option Board is installed, the Set Hold function holds BOTH current levels, as well as ALL relay settings.

Fault List

The Fault List screen is a read-only screen that allows the user to display the cause of the highest priority failure. The screen indicates the number of faults present in the system and a message detailing the highest priority fault present. Note that some faults can result in multiple displayed failures due to the high number of internal tests occurring. As faults are corrected, they are immediately cleared.

Faults are not stored; therefore, they are immediately removed if power is cycled. If the problem causing the faults still exists, however, faults will be displayed again after power is re-applied and a period of time elapses during which the diagnostic system re-detects them. The exception to this rule is the calibration failure. When a calibration fails, no corrupt data is stored. Therefore, the system continues to function normally on the data that was present before the calibration was attempted.

After 30 minutes or if power to the transmitter is cycled, the failure for calibration will be cleared until calibration is attempted again. If the problem still exists, the calibration failure will re-occur. Press ENTER to initiate view of the highest priority failure. The display will automatically return to normal after a few seconds.

Sim Out

The Sim Out function allows the user to simulate the dissolved oxygen level of the instrument. The user enters a ppm value directly onto the screen, and the output responds as if it were actually receiving the signal from the sensor. This allows the user to check the function of attached monitoring equipment during set-up or troubleshooting. Escaping this screen returns the unit to normal operation. Press ENTER to initiate the user entry mode, and the right-most digit of the value will flash. Use arrow keys to modify desired value and press ENTER to update.

The starting display value will be the last read value of the input. The output will be under control of the SIM screen until the ESC key is pressed.

Note: If the HOLD function is engaged before the Sim Output function is engaged, the simulated output will remain the same even when the ESC key is pressed. Disengage the HOLD function to return to normal output.

PID Timer

This function sets a timer to monitor the amount of time the PID controller remains at 0% or 100%. This function only appears if the PID controller is enabled. If the timer is set to 0000, the feature is effectively disabled.

If the timer value is set to any number other zero, a FAIL condition will occur if the PID controller remains at 0% or 100% for the timer value. If one of the relays are set to FAIL mode, this failure condition can be signaled by a changing relay contact.

Press ENTER to initiate user entry mode, and the entire value will flash. Use the UP arrow key to modify desired value; range of value is 0-9999 seconds. Press ENTER to store the new value.

Fail Out

This function enables special output condition for the main current loop output under a FAIL condition. When the Relay Option Board is installed, the display will read **Fail Out #1**. When enabled to **ON**, the output may be forced to the current value set in **Fail Val** (next item.)

With the Fail Out setting of ON, and a Fail Val setting of 6.5 mA, any alarm condition will cause the current loop output to drop outside the normal operating range to exactly 6.5 mA, indicating a system failure that requires attention.

Press ENTER to initiate user entry mode, and the entire value will flash. Use the UP arrow key to modify desired value; selections are **ON, OFF**. Press ENTER to store the new value.

Fail Val

Sets the output failure value for Out#1. When **Fail Out** above is set to **ON**, this function sets value of the current loop under a FAIL condition. When the Relay Option Board is installed, the display will read **Fail Out #1**. The output may be forced to any current value between 4-20 mA.

Press ENTER to initiate user entry mode, and the entire value will flash. Use the UP arrow key to modify desired value; selections are between **4mA**, and **20mA**. Press ENTER to store the new value.

Fail Out #2

This function sets the fail-mode of current loop output #2 under a FAIL condition. The settings and operation are identical to Fail Out for output #1.

Fail Val #2

This function sets the value of current loop output #2 under a FAIL condition. The settings and operation are identical to Fail Out for output #1.

Failsafe

This function allows the user to set the optional system relays to a failsafe condition. In a failsafe condition, the relay logic is reversed so that the relay is electrically energized in a normal operating state.

By doing this, the relay will not only change state when, for example, a dissolved oxygen limit is exceeded, but also when power is lost to the controller.

When failsafe is selected to be ON, the normally-open contacts of the relay will be closed during normal operation. In an attempt to make this configuration less confusing, the LCD icon logic is reversed with this setting, and the icon is OFF under this normal condition. Therefore, when the trip condition occurs, the closed N.O. contacts will be opened (relay de-energized), and the LCD icon will illuminate. In addition, a power fail would also cause the same contacts to open.

Default All

The Default All function allows the user to return the instrument back to factory default data for all user settings. It is intended to be used as a last resort troubleshooting procedure.

All user settings are returned to the original factory values. Hidden factory calibration data remains unchanged. Press ENTER to initiate user entry mode and the value **NO** will flash. Use the UP arrow key to modify value to **YES** and press ENTER to reload defaults.

Part 6 – Calibration

6.1 General

The instrument must be calibrated periodically to maintain a high degree of measurement accuracy. A complete calibration will include zeroing and spanning the sensor. It is generally unnecessary to set the zero at every calibration, however, it should be done during the initial installation.

The output of the dissolved oxygen sensor will degrade over the cartridge lifetime as the electrolyte and electrodes are slowly consumed. Under normal conditions (3 - 5 ppm) the degradation occurs at a very slow rate. To account for this degradation, the Q45D system should be re-calibrated about every 2-3 months. The frequency of calibration must be determined by the application. High temperature applications or applications involving other extreme operating conditions may require more frequent calibration than those operating at more ambient levels. It is important for the user to establish a periodic calibration schedule for a particular application. Before calibrating with a new sensor for the first time, or whenever a sensor has been left unpowered for 10 days or more, first connect the sensor to the transmitter and allow the system to operate for at least 2 hours to properly polarize the cartridge electrodes. Failure to perform this conditioning can result in significantly higher than normal initial readings. Once the cartridge has been properly conditioned, the user must select the proper operating parameters, including atmospheric pressure and solution conductivity.

The system provides three methods of D.O. calibration: 1-Point (sample), and % Saturation (air cal), and Zero. These three methods are significantly different.

6.2 Dissolved oxygen Span Cal (1-spl)

The 1-Point (sample or comparison) method is intended to be primarily used as an on-line calibration; however, the sensor can be removed, cleaned and then calibrated in a bucket of clean water if necessary. During calibration, the system will display the current ppm reading and the user can manually enter a reference value from a lab sample or comparative reference instrument. In the Q45D system, the 1-Point calibration adjusts the slope of the sensor output response.

1. Determine whether the calibration will be done on-line or with the sensor removed and placed into a bucket of clean water. If the sensor is removed from the application, rinse and clean if necessary.
2. If the sensor has been removed and placed into a bucket of water, allow sensor to temperature equilibrate with the solution as much as possible. With the sensor coming from an application which differs greatly in temperature, the user may have to wait as much as 20 minutes. If the sensor is on-line, the user may want to set the output HOLD feature prior to calibration to lock out any output fluctuations.
3. Scroll to the CAL menu section using the MENU key and press ENTER or the UP arrow key. **Cal DO** will then be displayed.
4. Press the ENTER key. The screen will display a flashing **1-spl** for 1-point, a **%-sat** for Saturation air calibration, or a **3-zer** for zero calibration. Using the UP arrow key, set for a 1-spl calibration and press ENTER.
5. The system now begins acquiring data for the calibration value. As data is gathered, the units for ppm and temperature may flash. Flashing units indicate that this parameter is unstable. The calibration data point acquisition will stop only when the data remains stable for a pre-determined amount of time. This can be overridden by pressing ENTER.

If the data remains unstable for 10 minutes, the calibration will fail and the message **Cal Unstable** will be displayed.

6. The screen will display the last measured ppm value and a message will be displayed prompting the user for the lab value. The user must then modify the screen value with the arrow keys and press ENTER. The system then performs the proper checks.
7. If accepted, the screen will display the message **PASS** with the new slope reading, then it will return to the main measurement display. If the calibration fails, a message indicating the cause of the failure will be displayed and the FAIL icon will be turned on.

6.3 Dissolved Oxygen Span Air Cal (%-sat)

This is the recommended method for air temperatures greater than about 5 C; however, it requires that the sensor be removed from the process and cleaned. Once cleaned, the sensor is held in air and allowed time to adjust to the air temperature. As the sensor temperature equilibrates, the transmitter automatically calculates the new 100% saturation point utilizing the temperature readings and the barometric pressure user data. This method therefore requires no user input during calibration. **Note: It is very important to allow enough time for the sensor to completely temperature equilibrate with the surrounding air. This time is at least 10 minutes.**

This method requires that the sensor be removed from the process, and covered, shielding the sensor from direct sunlight. The sensor membrane must be dry for this procedure, and not submerged in liquid. This method requires no user input during calibration; however, if this is the first time the system is being installed and calibrated, make sure to enter the proper atmospheric pressure data and process conductivity data prior to calibration.

1. Remove the sensor from the process. Clean and rinse if necessary with water, paying particular attention to cleaning the membrane.
2. Cover the sensor, if necessary, to shield it from the direct rays of the sun. Remember, the membrane must not be submerged - it must be in the air letting the sensor hang, membrane downward, while powered.
3. Allow the system to operate undisturbed for at least 20 minutes. If the system is stable, the value on the display will increase to some PPM value and remain at that level. At that point, calibration can continue.
4. Scroll to the CAL menu section using the MENU key and press ENTER or the UP arrow key. **Cal D.O.** will then be displayed.
5. Press the ENTER key. The screen will display a flashing **1-spl** for 1-point, a **2-%sat** for Saturation air calibration, or a **3-zer** for zero calibration. Using the UP arrow key, set for a **2-sat** span calibration and press ENTER.

6. The display will prompt the user to hold the sensor in air and press ENTER. If the sensor has already been removed from the process and reached temperature equilibrium, press the ENTER key.
7. The system now begins acquiring data for the calibration value. As data is gathered, the units for ppm and temperature may flash. Flashing units indicate that this parameter is unstable.
8. The calibration data point acquisition will stop only when the data remains stable for a pre-determined amount of time (approximately 15-20 seconds.) This can be overridden by pressing ENTER. If the data remains unstable for 10 minutes, the calibration will fail and the message **Cal Unstable** will be displayed.
9. If accepted, the screen will display the message **PASS** with the new sensor slope reading, then it will return to the main measurement display. If the calibration fails, a message indicating the cause of the failure will be displayed and the FAIL icon will be turned on.
10. The range of acceptable values for sensor slope is 20% to 500%. It may be necessary to rebuild the sensor as described in section 5, Dissolved Oxygen Sensor Assembly.

Should the slope value remain out of range and result in calibration failures, review the Service Section of this manual, then contact the Service Dept. at ATI for further assistance.

6.4 Dissolved oxygen Zero Cal

Dissolved oxygen sensors have extremely low offset outputs at zero. For this reason, it is normally sufficient to simply leave the zero at the factory default of 0 mV. As an alternative, an electronic zero can be set by disconnecting the sensor from the cable and performing the steps below.

These steps below assume that the sensor has been prepared in accordance with section 4, Dissolved Oxygen Sensor Assembly, earlier in this manual. Note that the 2 hour waiting time in step 2 below is not required if the monitor has been running for 24 hours prior to zeroing. If the unit has been running with the sensor connected, the sensor will normally return to a stable zero within 15 minutes.

1. Remove the sensor from the application if necessary. Clean and rinse if required.
2. Place about an 3 inches of zero solution in a container large enough to immerse the end of the sensor. You can make a zero solution by adding about 2 teaspoons of powdered sodium sulfite to up to 1 gallon of water. Allow the sensor to sit undisturbed for at least 1 hour. Suspend sensor, DO NOT LET SENSOR SIT ON TIP.
3. Scroll to the CAL menu section using the MENU key and press ENTER or the UP arrow key. **Cal D.O.** will then be displayed.
4. Press the ENTER key. The screen will display a flashing **1-spl** for 1-point, a **2-%sat** for Saturation calibration, or a **3-zer** for zero calibration. Using the UP arrow key, set for a **2-Zer** zero calibration and press ENTER.
5. The system now begins acquiring data for the sensor zero calibration value. As data is gathered, the units for sensor millivolts (mV) and temperature may flash. Flashing units indicate that this parameter is unstable. The calibration data point acquisition will stop only when the data remains stable for a pre-determined amount of time. This can be overridden by pressing ENTER. If the data remains unstable for 10 minutes, the calibration will fail and the message **Cal Unstable** will be displayed.
6. If accepted, the screen will display the message **PASS** with the new sensor zero reading (offset), then it will return to the main measurement display. If the calibration fails, a message indicating the cause of the failure will be displayed and the FAIL icon will be turned on. The range of acceptable value for sensor offset is -40 mV to +40 mV. Should a FAIL occur, carefully inspect the sensor for a tear in the membrane. It will probably be necessary to rebuild the sensor as described in section 4, Dissolved Oxygen Sensor Assembly. Should the offset value remain high and result in calibration failures, review the Service

section of this manual, and then contact the service dept. at ATI for further assistance.

The sensor offset value in mV from the last zero calibration is displayed on the lower line of the Default Menu for information purposes.

6.5 Temperature Calibration

Calibration of the temperature circuit is rarely ever required. The temperature calibration sequence is essentially a 1-point offset calibration that allows adjustments of approximately ± 5 °C. The sensor temperature may be calibrated on line, or the sensor can be removed from the process and placed into a known solution temperature reference.

In any case, it is critical that the sensor be allowed to reach temperature equilibrium with the solution in order to provide the highest accuracy.

When moving the sensor between widely different temperature conditions, it may be necessary to allow the sensor to stabilize as much as one hour before the calibration sequence is initiated. If the sensor is on-line, the user may want to set the output HOLD feature prior to calibration to lock out any output fluctuations.

1. Scroll to the CAL menu section using the MENU key and **press ENTER or the UP arrow key.**
2. Press the UP arrow key until **Cal Temp** is displayed.
3. Press the ENTER key. The message **Place sensor in solution then press ENTER** will be displayed. Move the sensor into the calibration reference (if it hasn't been moved already) and wait for temperature equilibrium to be achieved. Press ENTER to begin the calibration sequence.
4. The calibration data gathering process will begin. The message Wait will flash as data is accumulated and analyzed. The °C or °F symbol may flash periodically if the reading is too unstable.

5. The message **Adjust value - press ENTER** will be displayed, and the right-most digit will begin to flash, indicating that the value can be modified. Using the UP and LEFT arrow keys, modify the value to the known ref solution temperature. Adjustments up to ± 5 °C from the factory calibrated temperature are allowed. Press ENTER.
6. Once completed, the display will indicate **PASS** or **FAIL**. If the unit fails, the temperature adjustment may be out of range, the sensor may not have achieved complete temperature equilibrium, or there may be a problem with the temperature element. In the event of calibration failure, it is recommended to attempt the calibration again immediately.

Part 7 – Sensor Cleaning System

7.1 General

The cleaner control system located in the D.O. system enclosure contains a number of components designed to supply pulses of high pressure air to the tip of the sensor. The main components and their function are as follows:

Compressor: The air compressor is a small DC powered diaphragm type compressor that delivers air at up to 30 PSI to the accumulator cylinder which is part of the system. The compressor cannot provide an output above 30 PSI (2 Bar) so no special pressure relief is required in the system.

Accumulator: The accumulator is a 3 1/2" diameter stainless steel chamber that is pressurized with air from the compressor. The accumulator allows a relatively high volume of air to be delivered with each cleaning pulse, increasing the effectiveness of the cleaner.

Solenoid Valve: The solenoid valve on the outlet of the accumulator controls the flow of cleaning pulses to the nozzle located on the sensor assembly. The solenoid is opened and closed under the control of the sequencing module.

The operation of the cleaner control system is completely automatic. There are no customer adjustments required. The only requirement is that the D.O. monitor be set for AUTO mode of operation and that the desired cleaning frequency be programmed.

7.2 Cleaner Sequence

The cleaner control system is designed to provide three 3-second pulses of pressurized air through a nozzle located within 1 inch of the sensor membrane. The nozzle directs the air blast at the center of the membrane, effectively blasting away accumulated coatings on the surface.

The cleaner sequence begins with the closure of relay B in the display module. This contact is connected to a sequence control circuit located in the terminal compartment of the monitor. The sequencing system contains a relay that turns on the compressor and releases air to the cleaner nozzle when the accumulator has been charged. The entire cycle takes about 90 seconds.

During the cycle, the compressor will run for 40 seconds to charge the accumulator. At this point, the sequencing system will open the solenoid valve for 3 seconds, discharging air through the solenoid valve and out to the cleaner nozzle at the sensor. This delivers a 3 second high velocity air blast across the membrane. After 3 seconds, the solenoid will close, allowing the accumulator to recharge for 20 seconds. This cycle repeats itself three times, after which the compressor shuts off. The solenoid will release the final air burst shortly after the compressor shuts off so that no pressure remains in the accumulator.

Once the air cleaning system has run through a cycle, it will remain in standby while waiting for the next activation signal from the D.O. monitor. This will normally occur every 24 hours, but can be activated manually at any time as explained previously.

The cleaner can be started **Manually** any time the monitor is in operation. From the Measure Menu, press the UP arrow until the bottom line of the display indicates "Tcycle xx Hrs". Then press and hold the ENTER key for about 3 seconds to start the cleaning cycle. You will hear the compressor activate.

7.3 Cleaner Malfunction Alarm

The Q45D/60 is supplied with a Clean Failure Detection alarm to indicate that the sensor cleaner system has failed to operate properly. This alarm circuit will indicate a failure condition if the Auto-Clean system fails to activate during a 24 hour period. The time period begins when power is applied to the unit.

The relay associated with this alarm is a SPST relay that can be configured with a jumper to operate either as a normally open (NO) or normally closed (NC) contact. The jumper is located inside the protective circuit cover in the terminal compartment of the monitor. Remove the cover of the compartment to access the jumper pins. The figure below indicates that the jumper needs to be removed to make the relay a Normally Open (NO) contact.

One method that can remotely indicate a failure of the cleaner system is to use the fail relay to interrupt the 4-20 mA output. To do this, the relay must be configured for normally closed operation (Factory Default), as shown in the Figure below. The output signal is then wired through the normally closed relay as shown. A cleaner failure will result in the relay contacts opening, resulting in a loss of signal at the control system. A power failure at the D.O. monitor would also result in a loss of this signal.

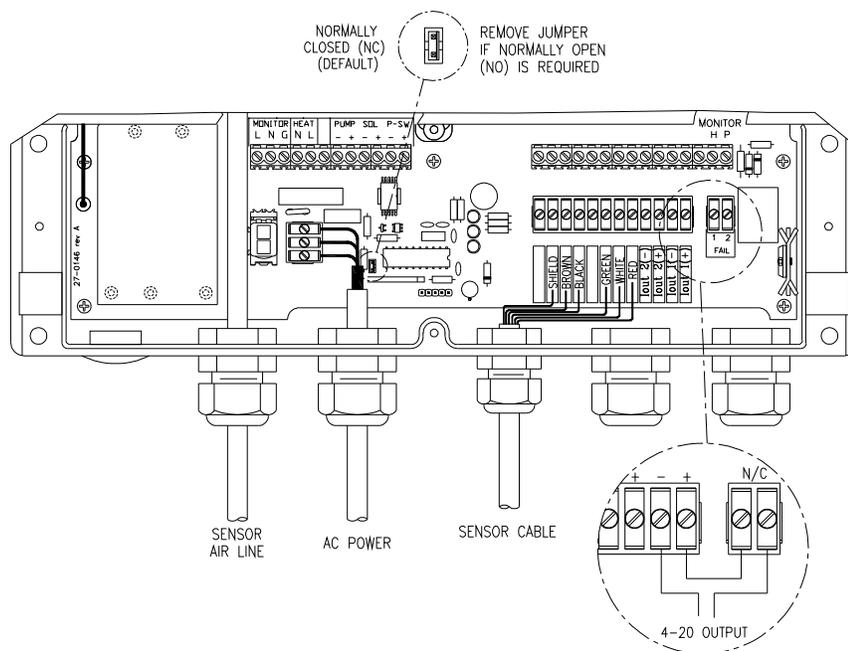


Figure 14 - Cleaner Failure Jumper Map Config (ATI-0582)

Part 8 – PID Controller Details

8.1 PID Description

PID control, like many other control schemes, are used in chemical control to improve the efficiency of chemical addition or control. By properly tuning the control loop that controls chemical addition, only the amount of chemical that is truly required is added to the system, saving money. The savings can be substantial when compared to a system which may be simply adding chemical at a constant rate to maintain some minimal addition under even the worst case conditions. The PID output controller is highly advantageous over simple control schemes that just utilize direct (proportional only) 4-20 mA output connections for control, since the PID controller can automatically adjust the “rate” of recovery based on the error between the setpoint and the measured value – which can be a substantial efficiency improvement..

The PID controller is basically designed to provide a “servo”action on the 4-20 mA output to control a process. If the user requires that a measured process stay as close as possible to a specific setpoint value, the controller output will change from 0% to 100% in an effort to keep the process at the setpoint. To affect this control, the controller must be used with properly selected control elements (valves, proper chemicals, etc.) that enable the controller to add or subtract chemical rapidly enough. This is not only specific to pumps and valves, but also to line sizes, delays in the system, etc.

This section is included to give a brief description of tuning details for the PID controller, and is not intended to be an exhaustive analysis of the complexities of PID loop tuning. Numerous sources are available for specialized methods of tuning that are appropriate for a specific application.

8.2 PID Algorithm

As most users of PID controllers realize, the terminology for the actual algorithm terms and even the algorithms themselves can vary between different manufacturers. This is important to recognize as early as possible, since just plugging in similar values from one controller into another can result in dramatically different results. There are various basic forms of PID algorithms that are commonly seen, and the implementation here is the most common version; The ISA algorithm (commonly referred to as the “ideal” algorithm.)

$$\text{output} = P \left[e(t) + \frac{1}{I} \int e(t) dt + D \frac{de(t)}{dt} \right]$$

Where:

output =	controller output
P =	proportional gain
I =	integral gain
D =	derivative gain
t =	time
e(t) =	controller error (e=measured variable – setpoint)

Figure 15 - Q45D PID Equation

The most notable feature of the algorithm is the fact the proportional gain term affects all components directly (unlike some other algorithms - like the “series” form.) If a pre-existing controller utilizes the same form of the algorithm shown above, it is likely similar settings can for made if the units on the settings are exactly the same. Be careful of this, as many times the units are the reciprocals of each other (i.e. reps-per-min, sec-per-rep.)

PID stands for “proportional, integral, derivative.” These terms describe the three elements of the complete controller action, and each contributes a specific reaction in the control process. The PID controller is designed to be primarily used in a “closed-loop” control scheme, where the output of the controller directly affects the input through some control device, such as a pump, valve, etc.

Although the three components of the PID are described in the setting area (section 5.25), here are more general descriptions of what each of the PID elements contribute to the overall action of the controller.

P Proportional gain. With no “I” or “D” contribution, the controller output is simply a

factor of the proportional gain multiplied by the input error (difference between the measured input and the controller setpoint.) Because a typical chemical control loop cannot react instantaneously to a correction signal, proportional gain is typically not efficient by itself – it must be combined with some integral action to be useful. Set the P term to a number between 2-4 to start. Higher numbers will cause the controller action to be quicker.

- I Integral gain. Integral gain is what allows the controller to eventually drive the input error to zero – providing accuracy to the control loop. It must be used to affect the accuracy in the servo action of the controller. Like proportional gain, increasing integral gain results in the control action happening quicker. Set the I term to a number between 3-5 to start (1-2 more than P). Like proportional gain, increasing the integral term will cause the controller action to be quicker.
- D Derivative gain. The addition of derivative control can be problematic in many applications, because it greatly contributes to oscillatory behavior. In inherently slow chemical control process', differential control is generally added in very small amounts to suppress erratic actions in the process that are non-continuous, such as pumps and valves clicking on and off. However, as a starting point for chemical process control, its best to leave the "D" term set to 0.

Therefore, based on these descriptions, the focus on tuning for chemical applications really only involves adjustment of "P" and "I" in most cases.

However, increasing both increases the response of the controller. The difference is in the time of recovery. Although combinations of high "P's" and low "I" will appear to operate the same as combinations of low "P's" and high "I's", there will be a difference in rate of recovery and stability. Because of the way the algorithm is structured, large "P's" can have a larger impact to instability, because the proportional gain term impacts all the other terms

directly. Therefore, keep proportional gain lower to start and increase integral gain to achieve the effect required.

Many tuning techniques have the user start with all values at 0, and then increase the P term until oscillations occur. The P value is then reduced to $\frac{1}{2}$ of the oscillatory value, and the I term is increased to give the desired response. This can be done with the Q45D controller, with the exception that the I term should start no lower than 1.0.

If it appears that even large amounts of integral gain (>20) don't appreciably increase the desired response, drop I back to about 1.0, and increase P by 1.00, and start increasing I again. In most chemical control schemes, I will be approximately 3 times the value of P.

8.3 Classical PID Tuning

Unlike many high speed position applications where PID loops are commonly used, the chemical feed application employed by this instrument does not require intense mathematical exercise to determine tuning parameters for the PID. In fact, the risk of instability is far greater with overly tuned PID control schemes. In addition, many of the classical mathematical exercises can be damaging or wasteful in the use of chemicals when the process is bumped with large amounts of input error to seek a response curve. Because of this, the general adjustment guidelines described in section 8.2 are sufficient for almost all application tuning for this instrument. Beyond this, many sources are available for classical tuning methods.

8.4 Manual PID Override Control

The Q45 PID output function allows the user to take manual control of the PID control signal. This is often useful when starting up a control loop, or in the event that you wish to bump the system manually to measure system response time.

To access the manual PID control, you must be in the MEASURE mode of operation and you must have the PID output displayed on the lower line. This line will indicate "XX.X% XX.X mA" with the X values simply indicating the current values. With this display on the screen, press and hold the ENTER key for about 5 seconds. You will see a small "m" show up between the % value and the mA value. This indicates you are now in manual mode.

Once in manual, you may increase the PID output by pressing the UP arrow or you may decrease the output by pressing the LEFT arrow. This will allow you to drive the PID output to any desired setting.

To revert to normal PID control, press and hold the ENTER key again until the “m” indicator disappears.

8.5 Common PID Pitfalls

The most common problem occurring in PID control applications involves the false belief that proper settings on only the PID controller can balance any process to an efficient level.

Closed-loop control can only be effective if all elements in the loop are properly selected for the application, and the process behavior is properly understood. Luckily, the nature of simple chemical control process are generally slow in nature. Therefore, even a de-tuned controller (one that responds somewhat slowly) can still provide substantial improvements to setpoint control. In fact, damaging oscillatory behavior is far more likely in tightly tuned controllers where the user attempted to increase response too much.

When deciding on a PID control scheme, it is important to initially review all elements of the process. Sticking valves, undersized pumps, or delays in reaction times associated with chemical addition can have a dramatic effect on the stability of the control loop. When controlling a chemical mix or reaction, the sensor should be placed in a location that ensures proper mixing or reaction time has occurred.

The easiest process' to control with closed-loop schemes are generally linear, and symmetrical, in nature. For example, controlling level in tank where the opening of valve for a fixed period of time corresponds linearly to the amount that flows into a tank. Chemical control process' can be more problematic when the nature of the setpoint value is non-linear relative to the input of chemical added. For example, pH control of a process may appear linear only in a certain range of operation, and become highly exponential at the extreme ranges of the measuring scale. In addition, if a chemical process is not symmetrical, that means it responds differently to the addition and subtraction of chemical. It is important in these applications to study steady-state impact as well as step-change impact to process changes. In other words, once the process has apparently been tuned under normal

operating conditions, the user should attempt to force a dramatic change to the input to study how the output reacts. If this is difficult to do with the actual process input (the recommended method), the user can place the control in manual at an extreme control point such as 5% or 95%, and release it in manual. The recovery should not be overly oscillatory. If so, the loop needs to be de-tuned to deal with that condition (reduce P and/or I.)

Part 9 – System Maintenance

9.1 General

The Q45D/60 Dissolved oxygen System will generally provide unattended operation over long periods of time. With proper care, the system should continue to provide measurements indefinitely. For reliable operation, maintenance on the system must be done on a regular schedule. Keep in mind that preventive maintenance on a regular schedule is much less troublesome than emergency maintenance that always seems to come at the wrong time.

9.2 Analyzer Maintenance

No unusual maintenance of the analyzer is required if installed according to the guidelines of this operating manual. If the enclosure door is frequently opened and closed, it would be wise to periodically inspect the enclosure sealing gasket for breaks or tears.

9.3 Sensor Maintenance

Sensor maintenance is required for accurate measurements. The primary requirement is simply to keep the sensor membrane clean. The membrane is a polymer material that is resistant to anything that will be encountered in water streams. However, deposits or biological growth can form on the surface of the membrane, and these deposits will reduce the sensitivity to oxygen. Normally, these coatings can be removed by simply wiping the membrane with a soft cloth or paper towel.

Should a coating form on the membrane that does not wipe off, it is best to change the membrane. Chemical cleaning may work as well, but a new membrane is a more reliable solution. To change a membrane, follow the Sensor Assembly procedure in this manual. Do not reuse the electrolyte from the sensor when changing a membrane. Always refill with fresh electrolyte. The electrolyte is stable and does not have a limited shelf life.

Even if no buildup is apparent on the membrane, it should be changed on a regular schedule. The recommended membrane change interval is every 6 months.

The actual membrane life is often in excess of one year, but periodic preventive maintenance will simply avoid having to do service on an emergency basis.

While the sensor is disassembled for membrane changing, examine the condition of the o-rings on both ends of the electrolyte canister. If the o-rings show any signs of damage, replace them with new ones from the spare parts kit. It is good practice to change these o-rings once a year, regardless of their condition.

9.31 Lead Anode Replacement

Galvanic D.O. sensors consume the lead electrode during normal operation. As oxygen is measured, lead is converted to lead oxide, and after a period of time, the lead is expended. The lead electrode in ATI's D.O. sensor cartridge can be easily replaced, and replacement should be done automatically every 12 months for best performance.

The lead electrode is the thick lead wire wrapped around the sensor body see Figure 9. It is connected through a stainless steel post with a nut and star washer. To change the lead electrode, remove the nut and washer and unwrap the old lead. Loop the end of a new lead electrode around the post and replace the nut and washer. Tighten the nut firmly but do not over tighten as damage to the sensing module can result. Wrap the remainder of the lead around the sensor body. There is no need to secure the other end of the lead.

Part 10 – Troubleshooting

10.1 General

The information included in this section is intended to be used in an attempt to quickly resolve an operational problem with the system. During any troubleshooting process, it will save the most time if the operator can first determine if the problem is related to the analyzer, sensor, or some external source. Therefore, this section is organized from the approach of excluding any likely external sources, isolating the analyzer, and finally isolating the sensor. If these procedures still do not resolve the operational problems, any results the operator may have noted here will be very helpful when discussing the problem with the factory technical support group.

10.2 External Sources of Problems

To begin this process, review the connections of the system to all external connections.

1. Verify the analyzer is earth grounded. For all configurations of the analyzer, an earth ground connection **MUST** be present for the shielding systems in the electronics to be active. Grounded conduit provides no earth connection to the plastic enclosure, so an earth ground wiring connection must be made at the power input terminal strip. Use the special “shield terminal” stub on the power supply board for optimum sensor cable shield grounding.
2. Verify the proper power input is present (115/230 VAC.)
3. Verify the loads on any 4-20 mA outputs do not exceed the limits in the Instrument Specifications (500 Ohms each for analyzer.) During troubleshooting, it is many times helpful to disconnect all these outputs and place wire-shorts across the terminals in the instrument to isolate the system and evaluate any problems which may be coming down the analog output connections.

4. Do not run sensor cables or analog output wiring in the same conduits as power wiring. If low voltage signal cables must come near power wiring, cross them at 90° to minimize coupling.
5. If rigid conduit has been run directly to the Q45D enclosure, check for signs that moisture has followed conduit into the enclosure.
6. Check for ground loops. Although the membrane sensor is electrically isolated from the process water, high frequency sources of electrical noise may still cause erratic behavior in extreme conditions. If readings are very erratic after wiring has been checked, check for a possible AC ground loop by temporarily placing the sensor into a bucket of water. The reading should be initially stable and then fall very slowly in a smooth fashion as the powered sensor depletes oxygen in the static sample directly at the sensor face.
7. On relay based systems, check the load that is connected to the relay contacts. Verify the load is within the contact rating of the relays. Relay contacts which have been used for higher power AC current loads may become unsuitable for very low signal DC loads later on because a small amount of pitting can form on the contacts. If the load is highly inductive (solenoids, motor starters, large aux relays), note that the contact rating will be de-rated to a lower level. Also, due to the large amount of energy present in circuits driving these types of loads when they are switched on an off, the relay wiring placement can result in electrical interference for other devices. This can be quickly resolved by moving wiring, or by adding very inexpensive snubbers (such As Quencharcs) to the load.
8. Carefully examine any junction box connections for loose wiring or bad wire stripping. If possible, connect the sensor directly to the analyzer for testing.
9. Check sensor membrane for fouling. Look closely for signs of grease or oil which may be present. Replace membrane and electrolyte, allow to stabilize, and re-check. The procedure in Oxygen Sensor Assembly, on page 21, must be followed when replacing the membrane.

10.3 Analyzer Tests

1. Disconnect power and completely disconnect all output wiring coming from the analyzer. Remove sensor wiring, relay wiring, and analog output wiring. Re-apply power to the analyzer. Verify proper voltage (115 or 230 VAC) is present on the incoming power strip of the analyzer, and that the analyzer power label matches the proper voltage value.
2. If analyzer does not appear to power up (no display), remove power and check removable fuse for continuity with a DVM.
3. Using a DVM, check the voltage across the BLUE and WHITE wires coming from the power supply board in the base of the enclosure. FIRST, disconnect any wiring going to I-out#1. Then, verify voltage across these wires is about 16-18 VDC when still connected to the terminal strip on the front half of the enclosure. If the BLUE and WHITE wires are not connected to the terminal strip on the front half of the enclosure, the voltage across them should measure about 29 VDC.
4. If analyzer does power up with a display, use the "Simulate" feature to check operation of the analog outputs (and relays contacts with a DVM.)
5. Check sensor power circuits. With a DVM, verify between -4.5 and -5.5 VDC from sensor connection terminals WHITE(+) to BLACK(-). Then verify between +4.5 and +5.5VDC from GREEN(+) to BLACK(-).
6. Check TC drive circuit. Place a wire-short between the RED and BLACK sensor terminals. With a DVM, measure the voltage between the BLACK(-) and BROWN(+) sensor terminals to verify that the TC drive circuit is producing about -4.6 to -5.5 VDC open-circuit. Remove DVM completely and connect a 1000 Ohm resistor across the BLACK to BROWN terminals. The temperature reading on the front LCD should display approximately 0°C and the dissolved oxygen reading should display approximately 0 ppm.

10.31 Display Messages

The Q45 Series instruments provide a number of diagnostic messages which indicate problems during normal operation and calibration. These messages appear as prompts on the secondary line of the display or as items on the Fault List.

MESSAGE	DESCRIPTION	POSSIBLE CORRECTION
Max is 200	Entry failed, maximum user value allowed is 200.	Reduce value to ≤ 200
Min is 200	Entry failed, minimum value allowed is 200.	Increase value to ≥ 200
Cal Unstable	Calibration problem, data too unstable to calibrate. Icons will not stop flashing if data is too unstable. User can bypass by pressing ENTER.	Clean sensor, get fresh cal solutions, allow temperature and conductivity readings to fully stabilize, do not handle sensor or cable during calibration.
Out of Range	Input value is outside selected range of the specific list item being configured.	Check manual for limits of the function to be configured.
Locked!	Transmitter security setting is locked.	Enter security code to allow modifications to settings.
Unlocked!	Transmitter security has just been unlocked.	Displayed just after security code has been entered.
Offset High	The sensor zero offset point is out of the acceptable range of -40 to +40 mV.	Check wiring connections to sensor. Allow sensor to operate powered a minimum of 12 hours prior to first zero cal.
Sensor High	The raw signal from the sensor is too high and out of instrument range.	Check wiring connections to sensor.
Sensor Low	The raw signal from the sensor is too low.	Check wiring connections to sensor.
D.O. High	The oxygen reading is greater than the maximum of the User-selected range.	The oxygen reading is over operating limits. Set measuring range to the next highest level.
Temp High	The temperature reading is $> 55^{\circ}\text{C}$.	The temperature reading is over operating limits. Check wiring and expected temp level. Perform RTD test as described in sensor manual. Recalibrate sensor temperature element if necessary.
Temp Low	The temperature reading is $< -10^{\circ}\text{C}$	Same as "Temp High" above.
TC Error	TC may be open or shorted.	Check sensor wiring and perform RTD test as described in sensor manual. Check j-box connections.

Figure 16 - Q45D Display Messages

MESSAGE	DESCRIPTION	POSSIBLE CORRECTION
D.O. Cal Fail	Failure of oxygen calibration. FAIL icon will not extinguish until successful calibration has been performed, or 30 minutes passes with no keys being pressed.	Clean sensor redo zero and span calibration. If still failure, sensor slope may be less than 20% or greater than 500%. Perform sensor tests as described in section 10.4. Replace sensor if still failure.
TC Cal Fail	Failure of temperature calibration. FAIL icon will not extinguish until successful calibration has been performed, or 30 minutes passes with no keys being pressed.	Clean sensor, check cal solution temperature and repeat sensor temp calibration. TC calibration function only allows adjustments of +/- 6 °C. If still failure, perform sensor tests as described in section 10.4. Replace sensor if still failure. .
EPROM Fail	Internal nonvolatile memory failure	System failure, consult factory.
Checksum Fail	Internal software storage error.	System failure, consult factory.
Display Fail	Internal display driver fail.	System failure, consult factory.
Range Cal Fail	Failure of factory temperature calibration.	Consult factory.

10.4 Sensor Tests

1. Check the membrane condition. A membrane that is not stretched smoothly across the tip of the sensor will cause unstable measurements. If necessary, change membrane and electrolyte.
2. Dissolved oxygen sensors can be tested with a digital voltmeter (DVM) to determine if a major sensor problem exists. Follow the steps below to verify sensor integrity:
 - A. Prior to disconnecting the sensor, measure the sensor output voltage at the analyzer terminal strip with a DVM while the sensor is hanging in air. If the sensor has been connected to a powered analyzer for at least 12 hours, the nominal output of the sensor will be about +400mVDC when measured in air at 25C (100% saturation) from BLACK(-) to RED(+) on the analyzer terminal strips. This value is affected by temperature, pressure, and age of the sensor so its possible to see a typical value that ranges from perhaps +200mVDC to about +800 mVDC under a wide range of conditions in air.
 - B. Disconnect the five sensor wires from the oxygen monitor. Those wires are color coded red, white, blue, green, brown, and black. Note: The brown wire may be replaced with a orange wire in some cables.
 - C. Remove the front sensor "cartridge" for the sensor body by unscrewing the cartridge at the large "knurl" in a counter clockwise manner. Inspect the gold RCA jack for signs of moisture or other foulants. Clean and thoroughly dry both connectors if necessary. Re-assemble when complete.
 - E. Connect the DVM between the brown and black wires. These are the RTD leads, and you should find a resistance value that depends on the temperature. The table below lists the resistance values for various temperatures.

Temperature °C	Resistance Ω
0	1000
5	1019
10	1039
15	1058
20	1078
25	1097
30	1117
35	1136
40	1155
45	1175
50	1194

Figure 17 - Pt100 RTD Table

If you suspect that water has gotten into a cable connection or into the plug connection of a submersible sensor, disconnect the cable and allow the parts of the sensor to sit in a warm place for 24 hours. If water in the connector is the problem, it should dry out sufficiently to allow normal sensor operation.

Spare Parts

<u>PART NO.</u>	<u>DESCRIPTION</u>
07-0011	D.O. Display Assembly, 115 VAC
07-0030	D.O. Display Assembly, 230 VAC
01-0317	Universal Autoclean PCB Assy
07-0097	Submersible D.O. Sensor with 30' cable
07-0099	Submersible D.O. Sensor with 60' cable
02-0007	Submersible D.O. sensing module
02-0014	Submersible D.O. sensing element body
02-0114	Submersible D.O. Sensing Holder Assembly with 30' cable
02-0115	Submersible D.O. Sensing Holder Assembly with 60' cable
45-0007	Electrolyte chamber
48-0001	Membrane holder, type 316 stainless steel
04-0003	Replacement lead electrode
05-0001*	Membranes, 5 mil., pkg. of 10
05-0014*	Spare Parts Kit, screw & o-ring
09-0007*	D.O. electrolyte, 4 oz (120 cc)
36-0040	Compression Pump, 12VDC
36-0041	Pump Mounting Kit
36-0039	Solenoid Valve, 12VDC
44-0040	PVC Tubing
23-0003	Fuse, 6.3A (Controller PCB)
23-0018	Fuse, 100 mA, 250V (115VAC Transmitter)
23-0019	Fuse, 50mA, 250V (230VAC Transmitter)
44-0276	Polyurethane Tubing, Black (sold /ft.)
54-0014	Heater Strip
26-0020	Pressure Switch
44-0290	1/8" NPT x 1/4" OD Instant Fitting (Mounted in Air Distribution Block)

Note: Instrument is supplied with sufficient spare parts for 6-12 months of operation. For 2 year spare parts inventory, 3 each of the items marked with an asterisk (*) should be ordered.